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Aug 2015



## FSB50760SFS Motion SPM<sup>®</sup> 5 SuperFET<sup>®</sup> Series

### Features

- UL Certified No. E209204 (UL1557)
- 600 V  $R_{DS(on)}$  = 530 m $\Omega$ (Max) SuperFET MOSFET 3-Phase Inverter with Gate Drivers and Protection
- Built-in Bootstrap Diodes Simplify PCB Layout
- Separate Open-Source Pins from Low-Side MOS-FETS for Three-Phase Current-Sensing
- Active-HIGH Interface, Works with 3.3 / 5 V Logic, Schmitt-trigger Input
- Optimized for Low Electromagnetic Interference
- HVIC Temperature-Sensing Built-in for Temperature Monitoring
- HVIC for Gate Driving and Under-Voltage Protection
- Isolation Rating: 1500 Vrms / 1 min.
- Moisture Sensitive Level (MSL) 3
- RoHS Compliant

### **Applications**

 3-Phase Inverter Driver for Small Power AC Motor Drives

### Related Source

- <u>RD-402 Reference Design for Motion SPM\_5 Super-</u> <u>FET Series</u>
- <u>AN-9082 Motion SPM5 Series Thermal Performance</u> <u>by Contact Pressure</u>
- <u>AN-9080 User's Guide for Motion SPM 5 Series V2</u>

### **General Description**

The FSB50760SFS is an advanced Motion SPM<sup>®</sup> 5 module providing a fully-featured, high-performance inverter output stage for AC Induction, BLDC and PMSM motors such as refrigerators, fans and pumps. These modules integrate optimized gate drive of the built-in MOSFETs(SuperFET<sup>®</sup> technology) to minimize EMI and while also providing multiple losses, on-module protection features including under-voltage lockouts and thermal monitoring. The built-in high-speed HVIC requires only a single supply voltage and translates the incoming logic-level gate inputs to the high-voltage, high-current drive signals required to properly drive the module's internal MOSFETs. Separate open-source MOSFET terminals are available for each phase to support the widest variety of control algorithms.



#### 3D Package Drawing (Click to Activate 3D Content)

### Package Marking & Ordering Information

Device Marking	Device	Package	Reel Size	Packing Type	Quantity
50760SFS	FSB50760SFS	SPM5Q-023	330mm	Tape-Reel	450

## **Absolute Maximum Ratings**

Inverter Part (each MOSFET unless otherwise specified.)

Symbol	Parameter	Conditions	Rating	Unit
V <sub>DSS</sub>	Drain-Source Voltage of Each MOSFET		600	V
*I <sub>D 25</sub>	Each MOSFET Drain Current, Continuous	$T_{C} = 25^{\circ}C$	3.6	А
*I <sub>D 80</sub>	Each MOSFET Drain Current, Continuous	$T_{C} = 80^{\circ}C$	2.7	А
*I <sub>DP</sub>	Each MOSFET Drain Current, Peak	T <sub>C</sub> = 25°C, PW < 100 μs	9.4	A
*I <sub>DRMS</sub>	Each MOSFET Drain Current, Rms	$T_{C} = 80^{\circ}C, F_{PWM} < 20 \text{ kHz}$	1.9	A <sub>rms</sub>
*P <sub>D</sub>	Maximum Power Dissipation	$T_{C} = 25^{\circ}C$ , For Each MOSFET	14.5	W

### Control Part (each HVIC unless otherwise specified.)

Symbol	Parameter	Conditions	Rating	Unit
V <sub>CC</sub>	Control Supply Voltage	Applied Between $V_{CC}$ and COM	20	V
V <sub>BS</sub>	High-side Bias Voltage	Applied Between $\rm V_B$ and $\rm V_S$	20	V
V <sub>IN</sub>	Input Signal Voltage	Applied Between IN and COM	$-0.3 \sim V_{CC} + 0.3$	V

Bootstrap Diode Part (each bootstrap diode unless otherwise specified.)

Symbol	Parameter	Conditions	Rating	Unit
V <sub>RRMB</sub>	Maximum Repetitive Reverse Voltage		600	V
* I <sub>FB</sub>	Forward Current	$T_{C} = 25^{\circ}C$	0.5	A
* I <sub>FPB</sub>	Forward Current (Peak)	$T_{C} = 25^{\circ}C$ , Under 1ms Pulse Width	1.5	А

### Thermal Resistance

Symbol	Parameter	Conditions	Rating	Unit
$R_{ extsf{ heta}JC}$	Junction to Case Thermal Resistance	Each MOSFET under Inverter Oper- ating Condition (1st Note 1)	8.6	°C/W

### **Total System**

Symbol	Parameter	Conditions	Rating	Unit
Τ <sub>J</sub>	Operating Junction Temperature		-40 ~ 150	°C
T <sub>STG</sub>	Storage Temperature		-40 ~ 125	°C
V <sub>ISO</sub>	Isolation Voltage	60 Hz, Sinusoidal, 1 Minute, Con- nect Pins to Heat Sink Plate	1500	V <sub>rms</sub>

1st Notes:

1. For the measurement point of case temperature  $\mathsf{T}_\mathsf{C},$  please refer to Figure 4.

2. Marking "\*" is calculation value or design factor.

Pin Description	
IC Common Supply Ground	
Bias Voltage for U-Phase High-Side MOSFET Driving	
Bias Voltage for U-Phase IC and Low-Side MOSFET Driving	
Signal Input for U-Phase High-Side	
Signal Input for U-Phase Low-Side	
No Connection	
Bias Voltage for V-Phase High Side MOSFET Driving	
Bias Voltage for V-Phase IC and Low Side MOSFET Driving	
Signal Input for V-Phase High-Side	
Signal Input for V-Phase Low-Side	
Output for HVIC Temperature Sensing	
Bias Voltage for W-Phase High-Side MOSFET Driving	
Bias Voltage for W-Phase IC and Low-Side MOSFET Driving	
Signal Input for W-Phase High-Side	
Signal Input for W-Phase Low-Side	
No Connection	
Positive DC-Link Input	
Output for U-Phase & Bias Voltage Ground for High-Side MOSF	ET Driving
Negative DC-Link Input for U-Phase	
Negative DC-Link Input for V-Phase	
Output for V-Phase & Bias Voltage Ground for High-Side MOSF	ET Driving

#### (1) COM (2) V<sub>B(U)</sub> (17) P ¥ (3) V<sub>CC(U)</sub> VCC VB (4) IN <sub>(UH)</sub> но HIN (18) U, V<sub>S(U)</sub> (5) IN <sub>(UL)</sub> vs LIN СОМ LO (6) N.C (19) N<sub>u</sub> (7) V<sub>B(V)</sub> (8) V<sub>CC(V)</sub> VCC VB (20) $N_{v}$ (9) IN <sub>(VH)</sub> HIN но (21) V, V<sub>S(V)</sub> (10) IN (VL) LIN vs СОМ LO Ż (11) VTS VTS (12) V B(W) VCC VB (22) N<sub>w</sub> (13) V<sub>CC(W)</sub> ▲ HIN но (14) IN (WH) (23) W, V<sub>S(W)</sub> (15) IN (WL) I IN vs сом 10 蒼 (16) N.C

#### 1st Notes:

3. Source terminal of each low-side MOSFET is not connected to supply ground or bias voltage ground inside Motion SPM® 5 product. External connections should be made as indicated in Figure 3.

Figure 1. Pin Configuration and Internal Block Diagram (Bottom View)

**Pin descriptions** 

**Pin Name** 

COM

V<sub>B(U)</sub>

V<sub>CC(U)</sub>

IN<sub>(UH)</sub>

IN<sub>(UL)</sub>

N.C

V<sub>B(V)</sub>

V<sub>CC(V)</sub>

IN<sub>(VH)</sub>

IN<sub>(VL)</sub>

 $V_{TS}$ 

V<sub>B(W)</sub>

V<sub>CC(W)</sub>

IN<sub>(WH)</sub>

IN<sub>(WL)</sub>

N.C

Р

U, V<sub>S(U)</sub>

NU

 $N_V$ V, V<sub>S(V)</sub>

 $N_W$ W, V<sub>S(W)</sub> Negative DC-Link Input for W-Phase

Output for W Phase & Bias Voltage Ground for High-Side MOSFET Driving

**Pin Number** 

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## **Electrical Characteristics** ( $T_J = 25^{\circ}C$ , $V_{CC} = V_{BS} = 15$ V unless otherwise specified.)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
BV <sub>DSS</sub>	Drain - Source Breakdown Voltage	V <sub>IN</sub> = 0 V, I <sub>D</sub> = 1 mA (2nd Note 1)	600	-	-	V
I <sub>DSS</sub>	Zero Gate Voltage Drain Current	V <sub>IN</sub> = 0 V, V <sub>DS</sub> = 600 V	-	-	1	mA
R <sub>DS(on)</sub>	Static Drain - Source Turn-On Resistance	$V_{CC} = V_{BS} = 15 \text{ V}, V_{IN} = 5 \text{ V}, I_D = 2 \text{ A}$	-	460	530	mΩ
V <sub>SD</sub>	Drain - Source Diode Forward Voltage	$V_{CC} = V_{BS} = 15 \text{ V}, V_{IN} = 0 \text{ V}, I_D = -2 \text{ A}$	-	-	1.1	V
t <sub>ON</sub>			-	1200	-	ns
t <sub>OFF</sub>		$V_{PN} = 300 \text{ V}, V_{CC} = V_{BS} = 15 \text{ V}, I_D = 2 \text{ A}$	-	970	-	ns
t <sub>rr</sub>	Switching Times	$V_{IN} = 0 V \leftrightarrow 5 V$ , Inductive Load L = 3 mH High- and Low-Side MOSFET Switching	-	160	-	ns
E <sub>ON</sub>		(2nd Note 2)	-	120	-	μJ
E <sub>OFF</sub>			-	10	-	μJ
RBSOA	Reverse Bias Safe Oper- ating Area	$      V_{PN} = 400 \text{ V}, \text{ V}_{CC} = \text{V}_{BS} = 15 \text{ V}, \text{ I}_{D} = \text{I}_{DP}, \text{ V}_{DS} = \text{BV}_{DSS}, $ $\text{T}_{J} = 150^{\circ}\text{C} $ High- and Low-Side MOSFET Switching (2nd Note 3)		Full	Square	

**Inverter Part** (each MOSFET unless otherwise specified.)

#### Control Part (each HVIC unless otherwise specified.)

Symbol	Parameter		Conditions	Min	Тур	Max	Unit
IQCC	Quiescent V <sub>CC</sub> Current	V <sub>CC</sub> = 15 V, V <sub>IN</sub> = 0 V	Applied Between $V_{CC}$ and COM	-	-	200	μA
I <sub>QBS</sub>	Quiescent V <sub>BS</sub> Current	V <sub>BS</sub> = 15 V, V <sub>IN</sub> = 0 V	Applied Between V <sub>B(U)</sub> - U, V <sub>B(V)</sub> - V, V <sub>B(W)</sub> - W	-	-	100	μΑ
UV <sub>CCD</sub>	Low-Side Under-Voltage	V <sub>CC</sub> Under-Voltage Protection Detection Level V <sub>CC</sub> Under-Voltage Protection Reset Level		7.4	8.0	9.4	V
UV <sub>CCR</sub>	Protection (Figure 8)			8.0	8.9	9.8	V
UV <sub>BSD</sub>	High-Side Under-Voltage	V <sub>BS</sub> Under-Voltage	V <sub>BS</sub> Under-Voltage Protection Detection Level		8.0	9.4	V
UV <sub>BSR</sub>	Protection (Figure 9)	V <sub>BS</sub> Under-Voltage	Protection Reset Level	8.0	8.9	9.8	V
V <sub>TS</sub>	HVIC Temperature Sens- ing Voltage Output	V <sub>CC</sub> = 15 V, T <sub>HVIC</sub> = 25°C (2nd Note 4)		600	790	980	mV
V <sub>IH</sub>	ON Threshold Voltage	Logic HIGH Level	Applied between IN and COM	-	-	2.9	V
V <sub>IL</sub>	OFF Threshold Voltage	Logic LOW Level	Applied between IN and COM	0.8	-	-	V

#### Bootstrap Diode Part (each bootstrap diode unless otherwise specified.)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>FB</sub>	Forward Voltage	I <sub>F</sub> = 0.1 A, T <sub>C</sub> = 25°C (2nd Note 5)	-	2.5	-	V
t <sub>rrB</sub>	Reverse Recovery Time	I <sub>F</sub> = 0.1 A, T <sub>C</sub> = 25°C	-	80	-	ns

#### 2nd Notes:

1. BV<sub>DSS</sub> is the absolute maximum voltage rating between drain and source terminal of each MOSFET inside Motion SPM<sup>®</sup> 5 product. V<sub>PN</sub> should be sufficiently less than this value considering the effect of the stray inductance so that V<sub>PN</sub> should not exceed BV<sub>DSS</sub> in any case.

t<sub>ON</sub> and t<sub>OFF</sub> include the propagation delay of the internal drive IC. Listed values are measured at the laboratory test condition, and they can be different according to the field applications due to the effect of different printed circuit boards and wirings. Please see Figure 6 for the switching time definition with the switching test circuit of Figure 7.

3. The peak current and voltage of each MOSFET during the switching operation should be included in the Safe Operating Area (SOA). Please see Figure 7 for the RBSOA test circuit that is same as the switching test circuit.

4.  $\mathsf{V}_{ts}$  is only for sensing-temperature of module and cannot shutdown MOSFETs automatically.

5. Built-in bootstrap diode includes around 15  $\Omega$  resistance characteristic. Please refer to Figure 2.

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Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V <sub>PN</sub>	Supply Voltage	Applied Between P and N	-	300	450	V
V <sub>CC</sub>	Control Supply Voltage	Applied Between $V_{CC}$ and COM	13.5	15.0	16.5	V
V <sub>BS</sub>	High-Side Bias Voltage	Applied Between $V_B$ and $V_S$	13.5	15.0	16.5	V
V <sub>IN(ON)</sub>	Input ON Threshold Voltage	Applied Patween IN and COM	3.0	-	V <sub>CC</sub>	V
V <sub>IN(OFF)</sub>	Input OFF Threshold Voltage	Applied Between IN and COM	0	-	0.6	V
t <sub>dead</sub>	Blanking Time for Preventing Arm-Short	$V_{CC}$ = $V_{BS}$ = 13.5 ~ 16.5 V, $T_{J} \leq 150^{\circ}C$	1.0	-	-	μs
f <sub>PWM</sub>	PWM Switching Frequency	T <sub>J</sub> ≤ 150°C	-	20	-	kHz

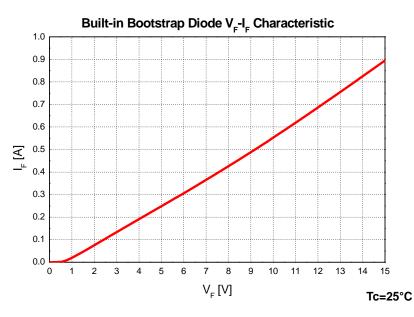
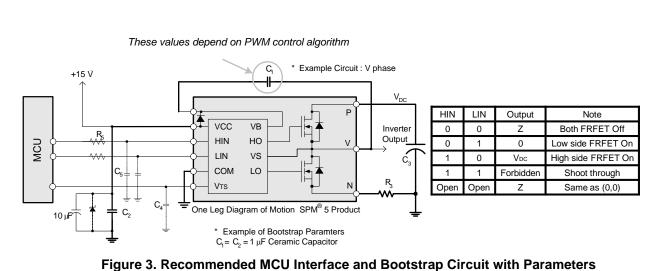
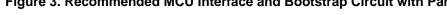


Figure 2. Built-in Bootstrap Diode Characteristics (Typical)

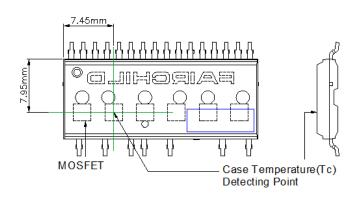
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#### 3rd Notes:

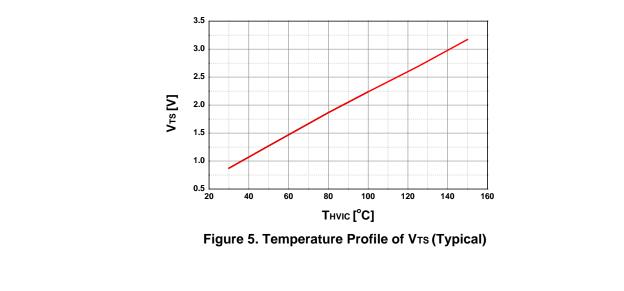
- 1. Parameters for bootstrap circuit elements are dependent on PWM algorithm. For 15 kHz of switching frequency, typical example of parameters is shown above.
- 2. RC-coupling (R<sub>5</sub> and C<sub>6</sub>) and C<sub>4</sub> at each input of Motion SPM 5 product and MCU (Indicated as Dotted Lines) may be used to prevent improper signal due to surge-noise.
- Bold lines should be short and thick in PCB pattern to have small stray inductance of circuit, which results in the reduction of surge-voltage. Bypass capacitors such as C<sub>1</sub>, C<sub>2</sub> and C<sub>3</sub> should have good high-frequency characteristics to absorb high-frequency ripple-current.



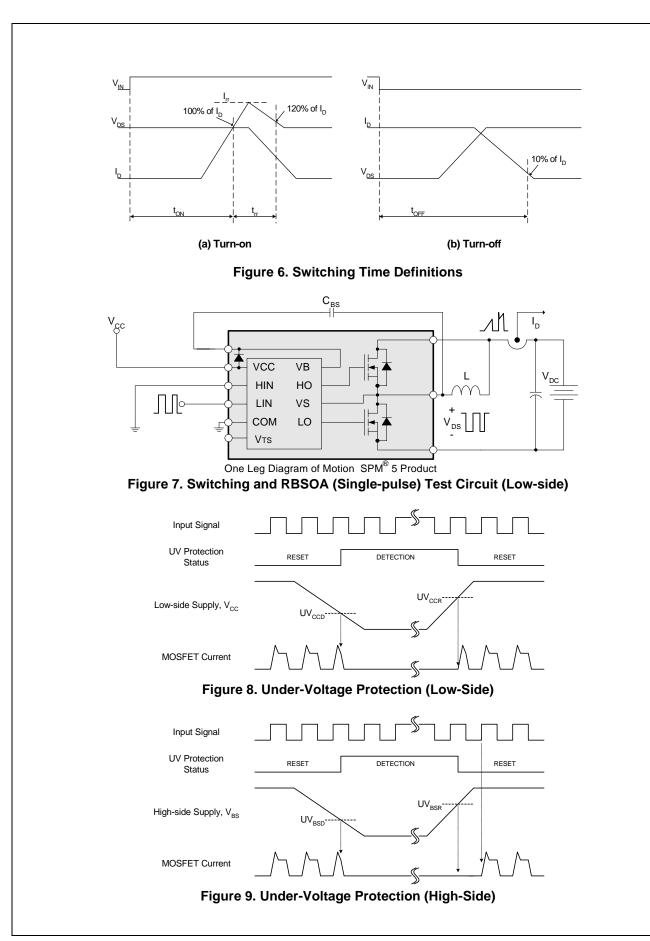
#### Figure 4. Case Temperature Measurement

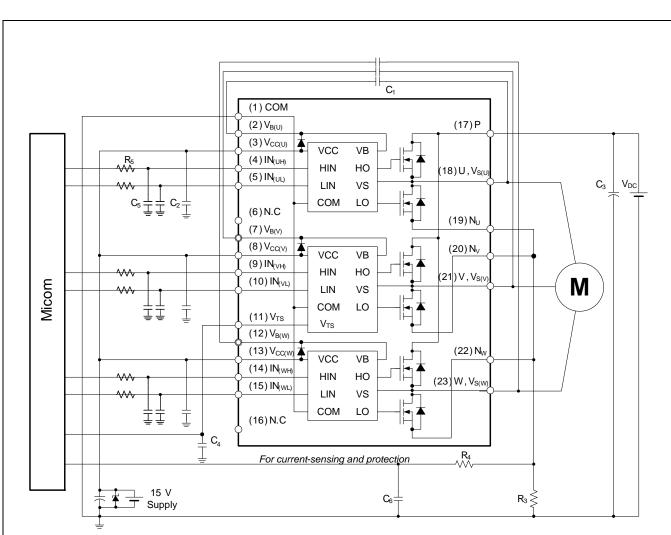
#### 3rd Notes:

4. Attach the thermocouple on top of the heat-sink of SPM 5 package (between SPM 5 package and heatsink if applied) to get the correct temperature measurement.



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### Figure 10. Example of Application Circuit

#### 4th Notes:

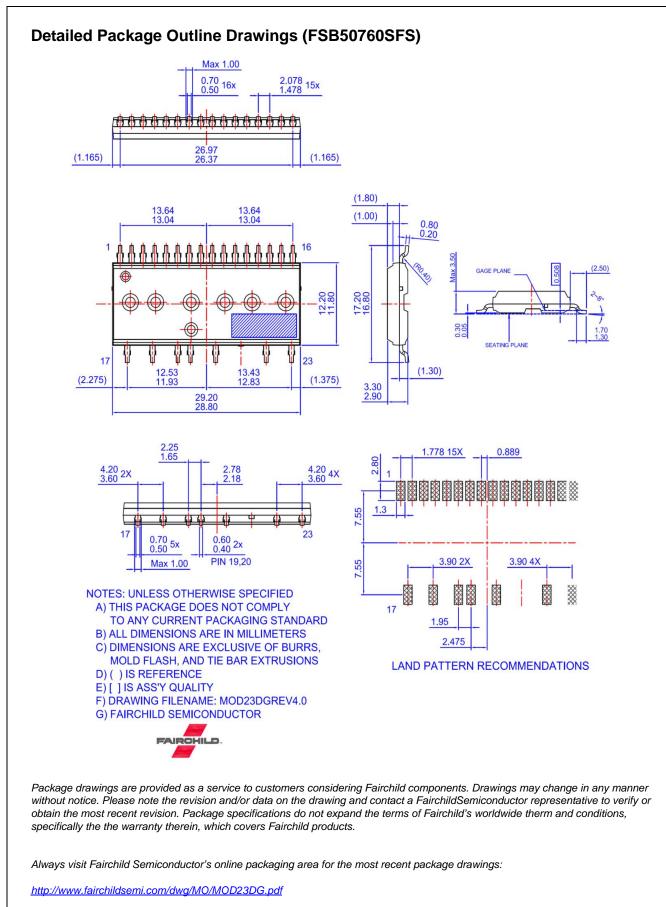
1. About pin position, refer to Figure 1.

2. RC-coupling (R<sub>5</sub> and C<sub>5</sub>, R<sub>4</sub> and C<sub>6</sub>) and C<sub>4</sub> at each input of Motion SPM<sup>®</sup> 5 product and MCU are useful to prevent improper input signal caused by surge-noise.

3. The voltage-drop across  $R_3$  affects the low-side switching performance and the bootstrap characteristics since it is placed between COM and the source terminal of the low-side MOSFET. For this reason, the voltage-drop across  $R_3$  should be less than 1 V in the steady-state.

4. Ground-wires and output terminals, should be thick and short in order to avoid surge-voltage and malfunction of HVIC.

5. All the filter capacitors should be connected close to Motion SPM 5 product, and they should have good characteristics for rejecting high-frequency ripple current.



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