

# 1 MSPS, Ultralow Power, 12-Bit ADC in 10-Lead LFCSP and MSOP

### **Data Sheet**

# AD7091R

#### FEATURES

#### Fast throughput rate of 1 MSPS Specified for V<sub>DD</sub> of 2.7 V to 5.25 V Logic voltage VDRIVE of 1.65 V to 5.25 V INL of ±1 LSB maximum Analog input range of 0 V to VREF Ultralow power 349 µA typical at 3 V and 1 MSPS 264 nA typical at 3 V in power-down mode Internal 2.5 V reference, ±4.5 ppm/°C typical drift Wide input bandwidth Flexible power/throughput rate management **High speed serial interface** SPI®/QSPI™/MICROWIRE™/DSP compatible **BUSY** indicator Power-down mode 10-lead, 3 mm × 2 mm LFCSP and 10-lead MSOP packages Temperature range of -40°C to +125°C

#### APPLICATIONS

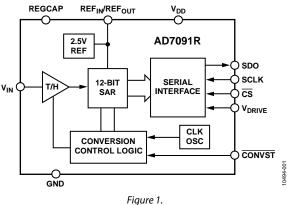
Battery-powered systems Handheld meters Medical instruments Mobile communications Instrumentation and control systems Data acquisition systems Optical sensors Diagnostic/monitoring functions Energy harvesting

#### **GENERAL DESCRIPTION**

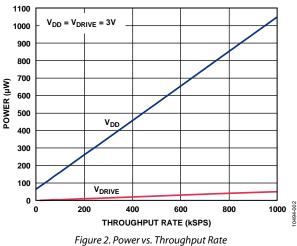
The AD7091R is a 12-bit successive approximation analog-todigital converter (ADC) that offers ultralow power consumption (typically 349  $\mu$ A at 3 V and 1 MSPS) while achieving fast throughput rates (1 MSPS with a 50 MHz SCLK). Operating from a single 2.7 V to 5.25 V power supply, the part contains a wide bandwidth track-and-hold amplifier that can handle input frequencies in excess of 7 MHz. The AD7091R also features an on-chip conversion clock, accurate reference, and high speed serial interface.

The conversion process and data acquisition are controlled using a CONVST signal and an internal oscillator. The AD7091R has a serial interface that allows data to be read after the conversion while achieving a 1 MSPS throughput rate.

#### FUNCTIONAL BLOCK DIAGRAM



The AD7091R uses advanced design and process techniques to achieve very low power dissipation at high throughput rates. An on-chip, accurate 2.5 V reference is available.



#### **PRODUCT HIGHLIGHTS**

- 1. Lowest Power 12-Bit SAR ADC Available.
- 2. On-Chip, Accurate 2.5 V Reference.
- 3. High Throughput Rate with Ultralow Power Consumption.
- 4. Flexible Power/Throughput Rate Management. Average power scales with the throughput rate. Power-down mode allows the average power consumption to be reduced when the device is not performing a conversion.
- Single Supply Operation with V<sub>DRIVE</sub> Function. The AD7091R operates from a single 2.7 V to 5.25 V supply. The V<sub>DRIVE</sub> function allows the serial interface to connect directly to 1.8 V to 3.3 V processors.

#### Rev. A

**Document Feedback** 

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#### **REVISION HISTORY**

5/15—Rev. 0 to Rev. A	
Changes to Serial Interface Section	6
8/12—Revision 0: Initial Version	

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## **SPECIFICATIONS**

 $V_{DD}$  = 2.7 V to 5.25 V,  $V_{DRIVE}$  = 1.65 V to 5.25 V,  $V_{REF}$  = 2.5 V internal reference,  $f_{SAMPLE}$  = 1 MSPS,  $f_{SCLK}$  = 50 MHz,  $T_A$  = -40°C to +125°C, unless otherwise noted.

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
DYNAMIC PERFORMANCE <sup>1</sup>	$f_{IN} = 10 \text{ kHz}$ sine wave		-76		
Signal-to-Noise Ratio (SNR) <sup>2</sup>		66.5	69		dB
	fsample = 500 kSPS	67.5	70		dB
Signal-to-Noise-and-Distortion Ratio (SINAD) <sup>2</sup>		66	69		dB
Total Harmonic Distortion (THD) <sup>2</sup>			-84	-79	dB
Spurious Free Dynamic Range (SFDR) <sup>2</sup>			-85	-78	dB
Aperture Delay <sup>2</sup>			5		ns
Aperture Jitter <sup>2</sup>			40		ps
Full Power Bandwidth <sup>2</sup>	At –3 dB		7.5		MHz
run ower bundwidth	At –0.1 dB		1.2		MHz
DC ACCURACY			1.2		101112
Resolution		12			Bits
Integral Nonlinearity (INL) <sup>2, 3</sup>		12			DILS
integral Noninearity (INE)	$V_{DRIVE} \leq 3.3 V$		±0 0	<b>⊥1</b>	LSB
	$V_{DRIVE} \ge 5.3 V$ $V_{DRIVE} > 3.3 V$ with external $V_{REF}$		±0.8	±1 ±1	LSB
Differential Neplinearity (DNI)			102		LSB
Differential Nonlinearity (DNL) <sup>2</sup> Offset Error <sup>2</sup>	Guaranteed no missing codes to 12 bits		±0.3	±0.9	
			±0.6	±2	LSB
Gain Error <sup>2</sup>			±0.8	±3	LSB
Total Unadjusted Error (TUE) <sup>2</sup>			-2		LSB
ANALOG INPUT				. <i>.</i>	
Input Voltage Range		0		V <sub>REF</sub>	V
DC Leakage Current				±1	μΑ
Input Capacitance <sup>4</sup>					_
	During acquisition phase		7		pF
	Outside acquisition phase		1		pF
VOLTAGE REFERENCE INPUT/OUTPUT					
REFour		2.485	2.5	2.525	V
REFIN		2.7		V <sub>DD</sub>	V
Drift			±4.5	±25	ppm/°C
LOGIC INPUTS					
Input High Voltage (V <sub>INH</sub> )		$0.7  imes V_{DRIVE}$			V
Input Low Voltage (V <sub>INL</sub> )				$0.3  imes V_{\text{DRIVE}}$	V
Input Current (I <sub>IN</sub> )	Typically 10 nA, $V_{IN} = 0 V$ or $V_{DRIVE}$			±1	μΑ
Input Capacitance (C <sub>IN</sub> ) <sup>4</sup>				5	pF
LOGIC OUTPUTS					
Output High Voltage (V <sub>он</sub> )	$I_{SOURCE} = 200 \mu A$	$V_{\text{DRIVE}} - 0.2$			V
Output Low Voltage (Vol)	I <sub>SINK</sub> = 200 μA			0.4	V
Floating State Leakage Current				±1	μA
Floating State Output Capacitance <sup>4</sup>				5	pF
Output Coding			Straight bi	nary	
CONVERSION RATE				· · · · · · · · · · · · · · · · · · ·	
Conversion Time				650	ns
Track-and-Hold Acquisition Time <sup>2, 4</sup>	Full-scale step input			350	ns
Throughput Rate	····· ···· ··· ···			1	MSPS

Parameter	Test Conditions/Comments	Min	Тур	Мах	Unit
POWER REQUIREMENTS			-76		
V <sub>DD</sub>		2.7		5.25	v
VDRIVE		1.65		5.25	V
DD	$V_{IN} = 0 V$			0.20	
Normal Mode—Static <sup>5</sup>					
	$V_{DD} = 5.25 V$		22	60	μA
	$V_{DD} = 3 V$		21.6	33	μA
Normal Mode—Operational					P
·····	$V_{DD} = 5.25 \text{ V},  \text{f}_{\text{SAMPLE}} = 1  \text{MSPS}$		388	449	μA
	$V_{DD} = 3 V$ , $f_{SAMPLE} = 1 MSPS$		349	408	μΑ
	$V_{DD} = 3 V$ , $f_{SAMPLE} = 100 kSPS$		55		μA
Power-Down Mode					F
	$V_{DD} = 5.25 V$		0.334	4.4	μA
	$V_{DD} = 5.25 \text{ V}, T_A = -40^{\circ}\text{C to} + 85^{\circ}\text{C}$		0.334	1.4	μA
	$V_{DD} = 3 V$		0.264	4.2	μA
	$V_{DD} = 3 V, T_A = -40^{\circ}C \text{ to } +85^{\circ}C$		0.264	1.2	μA
I <sub>DRIVE</sub>	$V_{IN} = 0 V$				
Normal Mode—Static <sup>6</sup>					
	$V_{DRIVE} = 5.25 V$		32	500	nA
	$V_{DRIVE} = 3 V$		28	500	nA
Normal Mode—Operational					
·	$V_{DRIVE} = 5.25 V$ , $f_{SAMPLE} = 1 MSPS$		42	86	μA
	$V_{DRIVE} = 3 V, f_{SAMPLE} = 1 MSPS$		17	20	μA
Power-Down Mode					
	$V_{DRIVE} = 5.25 V$		7	41	nA
	$V_{DRIVE} = 3 V$		2	28	nA
Total Power Dissipation (P <sub>DD</sub> + P <sub>DRIVE</sub> ) Normal Mode—Static <sup>5</sup>	$V_{IN} = 0 V$				
	$V_{DD} = V_{DRIVE} = 5.25 V$		116	318	μW
	$V_{DD} = V_{DRIVE} = 3 V$		65	101	μW
Normal Mode—Operational					
	$V_{DD} = V_{DRIVE} = 5.25 V$ , $f_{SAMPLE} = 1 MSPS$		2.3	2.9	mW
	$V_{DD} = V_{DRIVE} = 3 V$ , $f_{SAMPLE} = 1 MSPS$		1	1.3	mW
Power-Down Mode					
	$V_{DD} = V_{DRIVE} = 5.25 V$		1.8	24	μW
	$V_{DD} = V_{DRIVE} = 3 V$		0.8	13	μW

<sup>1</sup> Dynamic performance is achieved with a burst SCLK. Operating a free running SCLK during acquisition phase degrades dynamic performance. <sup>2</sup> See the Terminology section. <sup>3</sup> For  $V_{DRIVE} < V_{DD} + 0.7 V$ .

<sup>4</sup> Sample tested during initial release to ensure compliance. <sup>5</sup> SCLK is operating in burst mode and  $\overline{CS}$  is idling high. With a free running SCLK and  $\overline{CS}$  pulled low, the  $I_{DD}$  static current is increased by 30 µA typical at  $V_{DD} = 5.25$  V. <sup>6</sup> SCLK is operating in burst mode and  $\overline{CS}$  is idling high. With a free running SCLK and  $\overline{CS}$  pulled low, the  $I_{DD}$  static current is increased by 30 µA typical at  $V_{DD} = 5.25$  V.

#### TIMING SPECIFICATIONS

 $V_{DD}$  = 2.75 V to 5.25 V,  $V_{DRIVE}$  = 1.65 V to 5.25 V,  $T_A$  = -40°C to +125°C, unless otherwise noted.<sup>1</sup>

Table 2.			
Parameter	Limit at T <sub>MIN</sub> , T <sub>MAX</sub>	Unit	Description
fsclk	50	MHz max	Frequency of serial read clock
<b>t</b> 1	8	ns max	Delay from the end of a conversion until SDO three-state is disabled
t <sub>2</sub>	7	ns max	Data access time after SCLK falling edge
t <sub>3</sub>	0.4 t <sub>SCLK</sub>	ns min	SCLK high pulse width
<b>t</b> 4	3	ns min	SCLK to data valid hold time
t5	0.4 t <sub>SCLK</sub>	ns min	SCLK low pulse width
t <sub>6</sub>	15	ns max	SCLK falling edge to SDO high impedance
t7	10	ns min	CONVST pulse width
t <sub>8</sub>	650	ns max	Conversion time
<b>t</b> 9	6	ns min	CS low time before the end of a conversion
t <sub>10</sub>	18	ns max	Delay from $\overline{CS}$ until SDO three-state is disabled
t <sub>11</sub>	8	ns min	$\overline{CS}$ high time before the end of a conversion
<b>t</b> <sub>12</sub>	8	ns min	Delay from the end of a conversion until $\overline{CS}$ falling edge
t <sub>13</sub>	50	ms typ	Power-up time with internal reference <sup>2</sup>
	100	µs max	Power-up time with external reference
<b>t</b> quiet	50	ns min	Time between last SCLK edge and next CONVST pulse

 $^{\rm 1}$  Sample tested during initial release to ensure compliance.  $^{\rm 2}$  With a 2.2  $\mu F$  reference capacitor.

### **ABSOLUTE MAXIMUM RATINGS**

 $T_A = 25^{\circ}C$ , unless otherwise noted.

#### Table 3.

1 4010 51	
Parameter	Rating
V <sub>DD</sub> to GND	–0.3 V to +7 V
V <sub>DRIVE</sub> to GND	–0.3 V to +7 V
Analog Input Voltage to GND	$-0.3V$ to $V_{\text{REF}}+0.3V$
Digital Input Voltage to GND	-0.3 V to V <sub>DRIVE</sub> + 0.3 V
Digital Output Voltage to GND	-0.3 V to V <sub>DRIVE</sub> + 0.3 V
Input Current to Any Pin Except Supplies <sup>1</sup>	±10 mA
Operating Temperature Range	-40°C to +125°C
Storage Temperature Range	–65°C to +150°C
Junction Temperature	150°C
ESD	
HBM	±2.5 kV
FICDM	±1.5 kV

<sup>1</sup> Transient currents of up to 100 mA do not cause silicon controlled rectifier (SCR) latch-up.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

#### THERMAL RESISTANCE

#### Table 4. Thermal Resistance

Package Type	θ」Α	οισ	Unit
10-Lead LFCSP	33.2	4	°C/W
10-Lead MSOP	25.67	1.67	°C/W

#### **ESD CAUTION**



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

# **PIN CONFIGURATION AND FUNCTION DESCRIPTIONS**

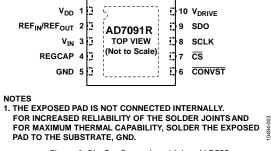


Figure 3. Pin Configuration, 10-Lead LFCSP

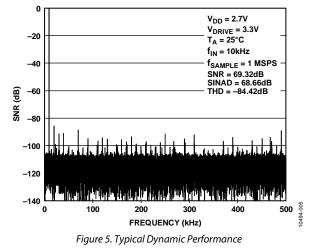


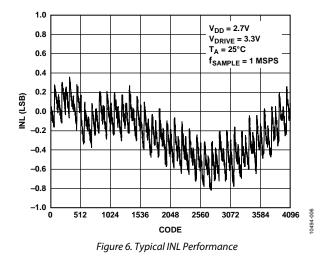
Figure 4. Pin Configuration, 10-Lead MSOP

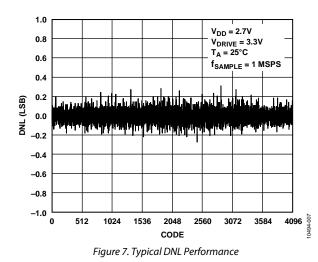
Table 5. Pir	Function	Descriptions
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Pin No.					
LFCSP	FCSP MSOP Mnemonic Description				
1	1	V <sub>DD</sub>	Power Supply Input. The V_DD range is from 2.7 V to 5.25 V. This supply pin should be decoupled to GND. The typical recommended values are 10 $\mu F$ and 0.1 $\mu F$ .		
2	2	REF <sub>IN</sub> /REF <sub>OUT</sub>	Voltage Reference Input Output. Decouple this pin to GND. The typical recommended decoupling capacitor value is 2.2 $\mu$ F. The user can either access the internal 2.5 V reference or overdrive the internal reference with an externally applied voltage. The reference voltage range for an externally applied reference is 2.7 V to V <sub>DD</sub> .		
3	3	VIN	Analog Input. The single-ended analog input range is from 0 V to $V_{REF}$ .		
4	4	REGCAP	Decoupling Capacitor Pin for Voltage Output from Internal Regulator. This output pin should be decoupled separately to GND using a 1 $\mu$ F capacitor. The voltage at this pin is 1.8 V typical.		
5	5	GND	Analog Ground. This pin is the ground reference point for all circuitry on the AD7091R. The analog input signal should be referred to this GND voltage.		
6	6	CONVST	Convert Start. Active low edge triggered logic input. The falling edge of CONVST places the track- and-hold into hold mode and initiates a conversion.		
7	7	CS	Chip Select. Active low logic input. The serial bus is enabled when $\overline{CS}$ is held low, and in this mode $\overline{CS}$ is used to frame the output data on the SPI bus.		
8	8	SCLK	Serial Clock. This pin acts as the serial clock input.		
9	9	SDO	Serial Data Output. The conversion output data is supplied to this pin as a serial data stream. The bits are clocked out on the falling edge of the SCLK input. The data is provided MSB first.		
10	10	V <sub>DRIVE</sub>	Logic Power Supply Input. The voltage supplied at this pin determines the operating voltage of the interface. Decoupling capacitors should be connected between $V_{DRIVE}$ and GND. The typical recommended values are 10 $\mu$ F and 0.1 $\mu$ F. The voltage range of this pin is 1.65 V to 5.25 V.		
11	N/A	EPAD	Exposed Pad. The exposed pad is not connected internally. For increased reliability of the solder joints and for maximum thermal capability, solder the exposed pad to the substrate, GND.		

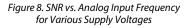
## **TYPICAL PERFORMANCE CHARACTERISTICS**







72 70 2.7V 68 3.0V 5.0V SNR (dB) 66 64 62 T<sub>A</sub> = 25°C 60 10 100 1 0494-INPUT FREQUENCY (kHz)



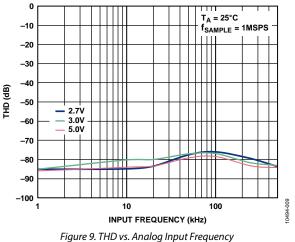


Figure 9. THD vs. Analog Input Frequency for Various Supply Voltages

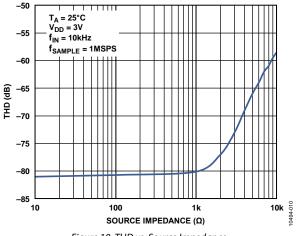


Figure 10. THD vs. Source Impedance

### **Data Sheet**

# AD7091R

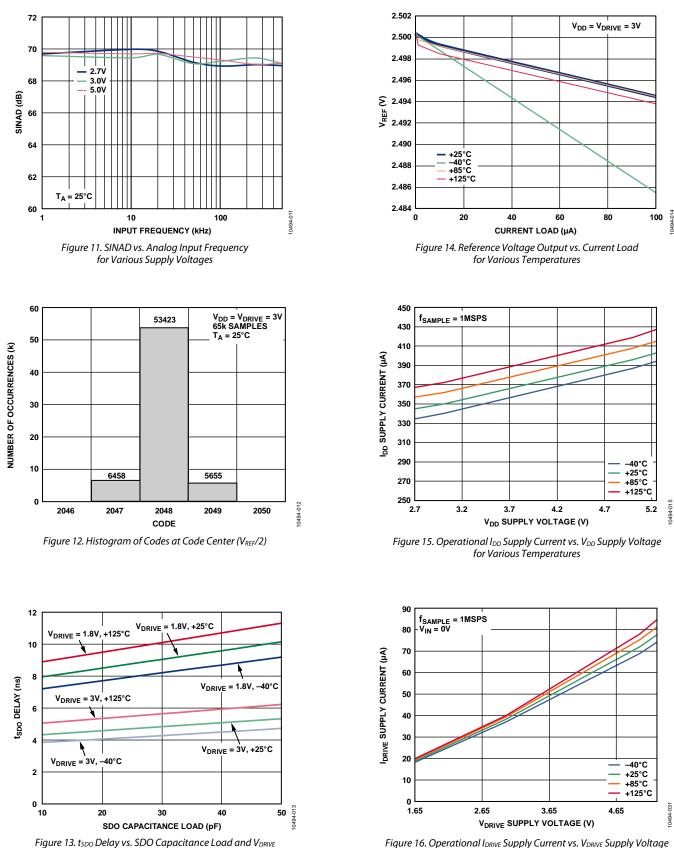


Figure 16. Operational IDRIVE Supply Current vs. VDRIVE Supply Voltage for Various Temperatures

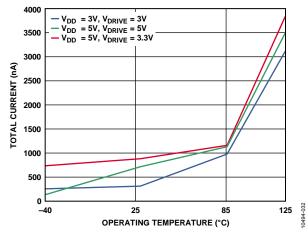


Figure 17. Total Power-Down Supply Current (I<sub>DD</sub> and I<sub>DRIVE</sub>) vs. Temperature for Various Supply Voltages

### TERMINOLOGY

#### Integral Nonlinearity (INL)

INL is the maximum deviation from a straight line passing through the endpoints of the ADC transfer function. For the AD7091R, the endpoints of the transfer function are zero scale (a point 0.5 LSB below the first code transition) and full scale (a point 0.5 LSB above the last code transition).

#### Differential Nonlinearity (DNL)

DNL is the difference between the measured and the ideal 1 LSB change between any two adjacent codes in the ADC.

#### **Offset Error**

Offset error is the deviation of the first code transition (00 ... 000) to (00 ... 001) from the ideal (such as GND + 0.5 LSB).

#### **Gain Error**

Gain error is the deviation of the last code transition (111 ... 110) to (111 ... 111) from the ideal (such as  $V_{REF} - 1.5$  LSB) after the offset error has been adjusted out.

#### Track-and-Hold Acquisition Time

The track-and-hold amplifier returns to track mode after the end of a conversion. The track-and-hold acquisition time is the time required for the output of the track-and-hold amplifier to reach its final value, within  $\pm 0.5$  LSB, after a conversion (see the Serial Interface section for more details).

#### Signal-to-Noise Ratio (SNR)

SNR is the measured ratio of signal to noise at the output of the ADC. The signal is the rms amplitude of the fundamental. Noise is the sum of all nonfundamental signals up to half the sampling frequency ( $f_{SAMPLE}/2$ ), excluding dc.

The ratio is dependent on the number of quantization levels in the digitization process: the more levels, the smaller the quantization noise. The theoretical signal-to-noise ratio for an ideal N-bit converter with a sine wave input is given by

Signal-to-Noise Ratio = (6.02N + 1.76) dB

Therefore, for a 12-bit converter, the SNR is 74 dB.

#### Signal-to-Noise-and-Distortion Ratio (SINAD)

SINAD is the measured ratio of signal to noise and distortion at the output of the ADC. The signal is the rms value of the sine wave, and noise is the rms sum of all nonfundamental signals up to half the sampling frequency ( $f_{SAMPLE}/2$ ), including harmonics, but excluding dc.

#### **Total Unadjusted Error (TUE)**

TUE is a comprehensive specification that includes the gain, linearity, and offset errors.

#### Total Harmonic Distortion (THD)

THD is the ratio of the rms sum of harmonics to the fundamental. For the AD7091R, THD is defined as

$$THD (dB) = 20 \log \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_5^2 + V_6^2}}{V_1}$$

where:

 $V_1$  is the rms amplitude of the fundamental.

 $V_2$ ,  $V_3$ ,  $V_4$ ,  $V_5$ , and  $V_6$  are the rms amplitudes of the second through the sixth harmonics.

#### Spurious Free Dynamic Range (SFDR)

SFDR, also known as peak harmonic or spurious noise, is defined as the ratio of the rms value of the next largest component in the ADC output spectrum (up to  $f_{SAMPLE}/2$  and excluding dc) to the rms value of the fundamental. Usually, the value of this specification is determined by the largest harmonic in the spectrum, but for ADCs where the harmonics are buried in the noise floor, the largest harmonic would be a noise peak.

#### **Aperture Delay**

Aperture delay is the measured interval between the leading edge of the sampling clock and the point at which the ADC samples data.

#### **Aperture Jitter**

Aperture jitter is the sample-to-sample variation in the effective point in time at which the data is sampled.

#### **Full Power Bandwidth**

Full power bandwidth is the input frequency at which the amplitude of the reconstructed fundamental is reduced by 0.1 dB or 3 dB for a full-scale input.

### THEORY OF OPERATION CIRCUIT INFORMATION

The AD7091R is a 12-bit successive approximation analog-todigital converter (ADC) that offers ultralow power consumption (typically 349  $\mu$ A at 3 V and 1 MSPS) while achieving fast throughput rates (1 MSPS with a 50 MHz SCLK). The part can be operated from a single power supply in the range of 2.7 V to 5.25 V.

The AD7091R provides an on-chip track-and-hold ADC with a serial interface housed in a tiny 10-lead LFCSP and 10-lead MSOP packages. These packages offer considerable space-saving advantages compared with alternative solutions. The serial clock input accesses data from the part. The clock for the successive approximation ADC is generated internally. The reference voltage for the AD7091R is generated internally by an accurate on-chip reference source. The analog input range for the AD7091R is 0 V to  $V_{REF}$ .

The AD7091R also features a power-down option to save power between conversions. The power-down feature is implemented across the standard serial interface as described in the Modes of Operation section.

#### **CONVERTER OPERATION**

The AD7091R is a successive approximation ADC based around a charge redistribution DAC. Figure 18 and Figure 19 show simplified schematics of the ADC. Figure 18 shows the ADC during its acquisition phase. SW2 is closed and SW1 is in Position A, the comparator is held in a balanced condition, and the sampling capacitor acquires the signal on  $V_{\rm IN}$ .

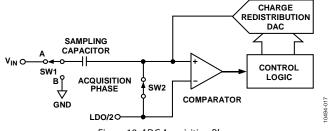
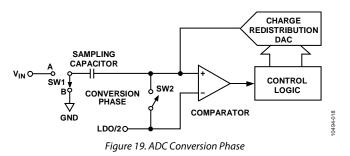


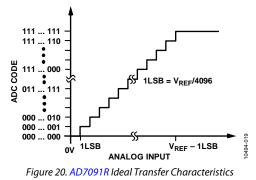
Figure 18. ADC Acquisition Phase

When the ADC starts a conversion, SW2 opens and SW1 moves to Position B (see Figure 19), causing the comparator to become unbalanced. The control logic and the charge redistribution DAC are used to add and subtract fixed amounts of charge from the sampling capacitor to bring the comparator back into a balanced condition. When the comparator is rebalanced, the conversion is complete. The control logic generates the ADC output code. Figure 20 show the ideal ADC transfer function.



#### ADC TRANSFER FUNCTION

The output coding of the AD7091R is straight binary. The designed code transitions occur midway between successive integer LSB values, such as 0.5 LSB, 1.5 LSB, and so on. The LSB size for the AD7091R is  $V_{REF}/4096$ . The ideal transfer characteristics for the AD7091R are shown in Figure 20.



#### **INTERNAL/EXTERNAL VOLTAGE REFERENCE**

The AD7091R allows the choice of an internal voltage reference or an external voltage reference.

The internal reference provides an accurate 2.5 V low temperature drift voltage reference. The internal reference is available at the REF<sub>IN</sub>/REF<sub>OUT</sub> pin. When using the internal reference, this pin should be decoupled using a capacitor with a typical value of 2.2  $\mu$ F to achieve the specified performance. With a fully discharged 2.2  $\mu$ F reference capacitor, the internal reference requires 50 ms typically to fully charge to the 2.5 V REF<sub>OUT</sub> voltage level.

In power-down mode, the internal voltage reference is shut down. After exiting power-down mode, adequate time should be allowed for the reference capacitor to recharge before performing a conversion. The time required to recharge the reference capacitor is dependent on the amount of charge remaining on the capacitor when exiting power-down mode.

If the on-chip reference is used externally to the AD7091R, it is recommended to buffer this reference before supplying the external circuitry.

Alternatively, the AD7091R reference voltage can be applied externally. If an external reference is applied to the device, the internal reference is automatically overdriven. An externally applied reference voltage should be in the range of 2.7 V to 5.25 V and should be connected to the REF<sub>IN</sub>/REF<sub>OUT</sub> pin.

#### **TYPICAL CONNECTION DIAGRAM**

Figure 22 shows a typical connection diagram for the AD7091R.

A positive power supply in the range of 2.7 V to 5.25 V should be connected to the V<sub>DD</sub> pin, with typical values for decoupling capacitors being 100 nF and 10 µF. These capacitors should be placed as close as possible to the device pins. With the power supply connected to the V<sub>DD</sub> pin, the AD7091R operates with the internal 2.5 V reference, and the REFIN/REFOUT pin should be decoupled using a capacitor with a typical value of 2.2 µF to achieve the specified performance and provide an analog input range of 0 V to VREF. The typical value for the regulator bypass decoupling capacitor (REGCAP) is 1 µF. The voltage applied to the V<sub>DRIVE</sub> input controls the voltage of the serial interface; therefore, this pin should be connected to the supply voltage of the microprocessor.  $V_{DRIVE}$  can be set in the range of 1.65 V to 5.25 V. Typical values for the VDRIVE decoupling capacitors are 100 nF and 10 µF. The conversion result is output in a 12-bit word with the MSB first.

The AD7091R requires the user to initiate a software reset upon power-up (see the Software Reset section).

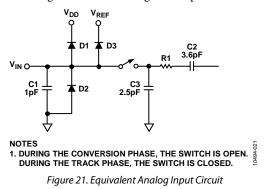
If an external reference is applied to the device, the internal reference is automatically overdriven. An externally applied reference voltage should be in the range of 2.7 V to 5.25 V and should be connected to the REF<sub>IN</sub>/REF<sub>OUT</sub> pin.

If the BUSY indicator feature is required, a pull-up resistor of typically 100 k $\Omega$  to  $V_{\text{DRIVE}}$  should be connected to the SDO pin. In addition, for applications in which power consumption is a concern, the power-down mode can be used to improve the power performance of the ADC (see the Modes of Operation section for more details).

#### **ANALOG INPUT**

Figure 21 shows an equivalent circuit of the AD7091R analog input structure. The D1 and D2 diodes provide ESD protection for the analog input. The D3 diode is a parasitic diode between  $V_{IN}$  and  $V_{REF}$ . To prevent the diodes from becoming forward-biased and from starting to conduct current, ensure that the

analog input signal never exceeds  $V_{REF}$  or  $V_{DD}$  by more than 300 mV. These diodes can conduct a maximum of 10 mA without causing irreversible damage to the part.



Capacitor C1 in Figure 21 is typically about 1 pF and can primarily be attributed to pin capacitance. Resistor R1 is a lumped component made up of the on resistance of a switch. This resistor is typically about 500  $\Omega$ . Capacitor C2 is the ADC sampling capacitor and typically has a capacitance of 3.6 pF.

In applications where harmonic distortion and signal-to-noise ratio are critical, the analog input should be driven from a low impedance source. Large source impedances significantly affect the ac performance of the ADC. This may necessitate using an input buffer amplifier as shown in Figure 22. The choice of the op amp is a function of a particular application.

When no amplifier is used to drive the analog input, the source impedance should be limited to low values. The maximum source impedance depends on the amount of total harmonic distortion (THD) that can be tolerated. The THD increases as the source impedance increases and performance degrades. Figure 10 shows a graph of THD vs. source impedance when using a supply voltage of 3 V and a sampling rate of 1 MSPS.

Use an external filter—such as a one-pole, low-pass RC filter, or similar, as shown in Figure 22—on the analog input connected to the AD7091R to achieve the specified performances.

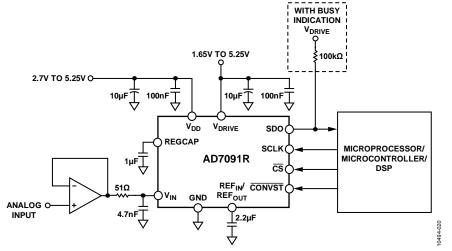


Figure 22. AD7091R Typical Connection Diagram

#### **MODES OF OPERATION**

The mode of operation of the AD7091R is selected by controlling the logic state of the  $\overrightarrow{\text{CONVST}}$  signal when a conversion is complete.

The logic level of the CONVST pin at the end of a conversion determines whether the AD7091R remains in normal mode or enters power-down mode (see the Normal Mode and Power-Down Mode sections). Similarly, if the device is already in power-down mode, CONVST controls whether the device returns to normal mode or remains in power-down mode. These modes of operation provide flexible power management options, allowing optimization of the ratio of the power dissipation to the throughput rate for different application requirements.

#### Normal Mode

The normal mode of operation is intended to achieve the fastest throughput rate performance. Users do not have to worry about power-up times because the AD7091R remains fully powered at all times. Figure 29 shows the general timing diagram of the AD7091R in normal mode.

In this mode, the conversion is initiated on the falling edge of  $\overline{\text{CONVST}}$ , as described in the Serial Interface section. To ensure that the part remains fully powered up at all times,  $\overline{\text{CONVST}}$  must return high after t<sub>7</sub> and remain high until the conversion is complete. At the end of a conversion (denoted as EOC in Figure 27), the logic state of  $\overline{\text{CONVST}}$  is tested.

To read back data stored in the conversion result register, wait until the conversion is complete, and then pull  $\overline{\text{CS}}$  low. The conversion data is subsequently clocked out on the SDO pin (see Figure 29). Because the output shift register is 12 bits wide, data is shifted out of the device as a 12-bit word under the control of the serial clock input (SCLK). After reading back the data, the user can pull  $\overline{\text{CONVST}}$  low again to start another conversion after the t<sub>QUIET</sub> time has elapsed.

#### Power-Down Mode

The power-down mode of operation is intended for use in applications where slower throughput rates and lower power consumption are required. In this mode, the ADC can be powered down either between each conversion or between a series of conversions performed at a high throughput rate, with the ADC powered down for relatively long durations between these bursts of several conversions. When the AD7091R is in power-down mode, the serial interface remains active even though all analog circuitry, including the internal voltage reference, is powered down.

To enter power-down mode, pull  $\overrightarrow{\text{CONVST}}$  low and keep it low until the end of a conversion (denoted as EOC in Figure 30). After the conversion is complete, the logic level of the  $\overrightarrow{\text{CONVST}}$  pin is tested. If the  $\overrightarrow{\text{CONVST}}$  signal is logic low at this point, the part enters power-down mode. The serial interface of the AD7091R is functional in powerdown mode; therefore, users can read back the conversion result after the part enters power-down mode.

To exit this mode of operation and power up the AD7091R, pull  $\overline{CONVST}$  high at any time. On the rising edge of  $\overline{CONVST}$ , the device begins to power up. The internal circuitry of the AD7091R requires 100 µs to power up from power-down mode. If the internal reference is used, the reference capacitor must be fully recharged before accurate conversions are possible.

To start the next conversion after exiting power-down mode, operate the interface as described in the Normal Mode section.

#### **POWER CONSUMPTION**

The two modes of operation for the AD7091R—normal mode and power-down mode (see the Modes of Operation section for more information)—produce different power vs. throughput rate performances. Using a combination of normal mode and power-down mode achieves the optimum power performance.

To calculate the overall power consumption, the  $I_{DRIVE}$  current should also be taken into consideration. Figure 16 shows the  $I_{DRIVE}$  current at various supply voltages. Figure 23 and Figure 24 show the power consumption for  $V_{DRIVE}$  with various throughput rates.

Improved power consumption for the AD7091R can be achieved by carefully selecting the  $V_{DD}$  and  $V_{DRIVE}$  supply voltages and the SDO line capacitance (see Figure 15 and Figure 16).

#### Normal Mode

With a 3 V V<sub>DD</sub> supply and a throughput rate of 1 MSPS, the I<sub>DD</sub> current consumption for the part in normal operational mode is 349  $\mu$ A (composed of 21.6  $\mu$ A of static current and 327.4  $\mu$ A of dynamic current during conversion). The dynamic current consumption is directly proportional to the throughput rate.

The following example calculates the power consumption of AD7091R when operating in normal mode with a 500 kSPS throughput rate and a 3 V supply.

The dynamic conversion time contributes 491  $\mu$ W to the overall power dissipation as follows:

 $((500 \text{ kSPS/1 MSPS}) \times 327.4 \text{ }\mu\text{A}) \times 3 \text{ V} = 491 \text{ }\mu\text{W}$ 

The contribution to the total power dissipated by the normal mode static operation is

 $21.6 \ \mu A \times 3 \ V = 65 \ \mu W$ 

Therefore, the total power dissipated at 500 kSPS is

 $491 \; \mu W + 65 \; \mu W = 556 \; \mu W$ 

#### Normal and Power-Down Mode Combination

A combination of normal mode and power-down mode achieves the optimum power performance.

The internal circuitry of the AD7091R requires 100  $\mu$ s to power up from power-down mode. Power-down mode can therefore be performed at sampling rates of less than 10 kSPS.

Recharging the reference capacitor should also be considered when using the on-chip reference. The AD7091R can fully charge a 2.2  $\mu$ F reference capacitor in typically 50 ms. However, the time to charge the reference capacitor is dependent on the amount of charge remaining on the capacitor when exiting power-down mode. The reference capacitor loses charge very slowly, resulting in much faster recharge times.

Figure 25 shows the AD7091R conversion sequence with a combination of normal mode and power-down mode with a throughput of 5 kSPS when using an external reference. With a  $V_{DD}$  supply voltage of 3 V, the static current is 21.6  $\mu$ A. The dynamic current is 327.4  $\mu$ A at 1 MSPS. The current consumption during power-down mode is 264 nA. A conversion requires 650 ns to complete, and the AD7091R requires 100  $\mu$ s to power up from power-down mode when using an external reference.

The dynamic conversion time contributes 4.9  $\mu$ W to the overall power dissipation as follows:

 $((5 \text{ kSPS/1 MSPS}) \times 327.4 \text{ }\mu\text{A}) \times 3 \text{ } \text{V} = 4.9 \text{ }\mu\text{W}$ 

The contribution to the total power dissipated by the normal mode static operation and power-down mode is

((100.6  $\mu s/200~\mu s) \times 21.6~\mu A) \times 3~V$  +

 $((99.4~\mu\text{s}/200~\mu\text{s})\times264~n\text{A})\times3~\text{V}=33~\mu\text{W}$ 

The conversion time of 650 ns is included in the static operation time.

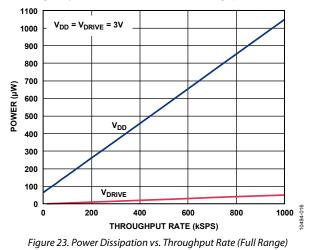
The total power dissipated at 5 kSPS is

 $4.9 \ \mu W + 33 \ \mu W = 37.9 \ \mu W$ 

Figure 23 and Figure 24 show the typical power vs. throughput rate for the AD7091R at 3 V for the  $V_{DD}$  supply and for the

 $V_{\text{DRIVE}}$  supply. Power consumption for the  $V_{\text{DRIVE}}$  supply can be calculated by the same principles as those for the  $V_{\text{DD}}$  supply.

Additionally, Figure 24 shows the reduction in power consumption that can be achieved when power-down mode is used compared with using only normal mode at lower throughput rates.



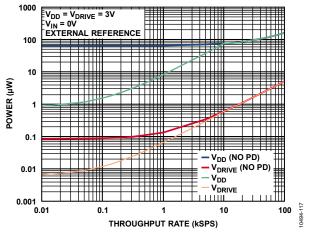


Figure 24. Power Dissipation vs. Throughput Rate (Lower Range)

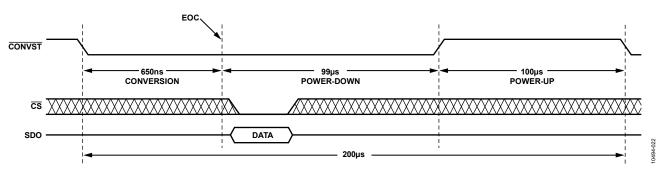


Figure 25. 10 SPS with Normal and Power-Down Mode

### **Data Sheet**

### SERIAL INTERFACE

The AD7091R serial interface consists of four signals: SDO, SCLK, CONVST, and CS. The serial interface is used for accessing data from the result register and controlling the modes of operation of the device. SCLK is the serial clock input for the device, and SDO data transfers take place with respect to this SCLK. The CONVST signal is used to initiate the conversion process and to select the mode of operation of the AD7091R (see the Modes of Operation section). CS is used to frame the data. The falling edge of CS takes the SDO line out of a high impedance state. A rising edge on CS returns the SDO to a high impedance state.

The logic level of  $\overline{CS}$  at the end of a conversion determines whether the BUSY indicator feature is enabled. This feature affects the propagation of the MSB with respect to  $\overline{CS}$  and SCLK.

#### WITH BUSY INDICATOR

When the BUSY indicator feature is enabled, the SDO pin can be used as an interrupt signal to indicate that a conversion is complete. The connection diagram for this configuration is shown in Figure 26. Note that a pull-up resistor to  $V_{DRIVE}$  is required on the SDO pin. This allows the host to detect when the SDO pin exits the three-state condition after the end of a conversion. In this mode, 13 SCLK cycles are required: 12 clock cycles to propagate out the data and an additional clock cycle to return the SDO pin to the three-state condition.

To enable the BUSY indicator feature, a conversion should first be started. A high-to-low transition on CONVST initiates a conversion. This puts the track-and-hold into hold mode and samples the analog input at this point. If the user does not want the AD7091R to enter power-down mode, CONVST should be taken high before the end of the conversion. A conversion requires 650 ns to complete. When the conversion process is finished, the track-and-hold goes back to track mode. Before the end of a conversion, pull  $\overline{CS}$  low to enable the BUSY indicator feature. The busy indicator is not valid for this first conversion, only on subsequent conversions. The user must ensure that  $\overline{CS}$  is pulled low before the end of each conversion to keep the busy indicator enabled.

The conversion result is shifted out of the device as a 12-bit word under the control of SCLK and the logic state of  $\overline{CS}$  at the end of a conversion. At the end of a conversion, SDO is driven low. SDO remains low until the MSB (DB11) of the conversion result is clocked out on the first falling edge of SCLK. DB10 to DB0 are shifted out on the subsequent falling edges of SCLK. The 13<sup>th</sup> SCLK falling edge returns SDO to a high impedance state. Data is propagated on SCLK falling edges and is valid on both the rising and falling edges of the next SCLK. The timing diagram for this mode is shown in Figure 27.

If another conversion is required, pull  $\overline{\text{CONVST}}$  low again and repeat the read cycle.

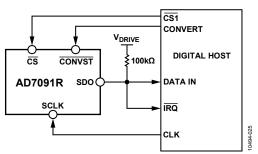
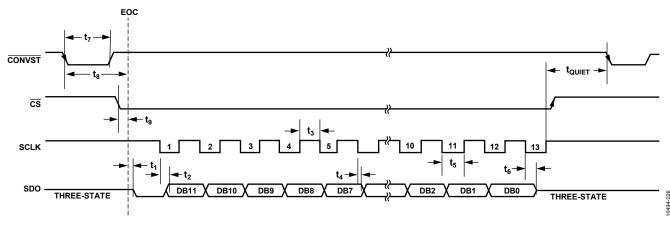
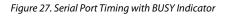


Figure 26. Connection Diagram with BUSY Indicator



NOTES

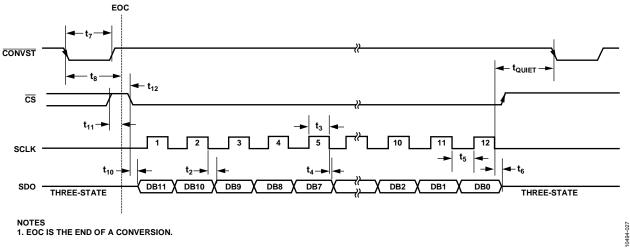
1. EOC IS THE END OF A CONVERSION.

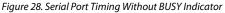


#### WITHOUT BUSY INDICATOR

To operate the AD7091R without the BUSY indicator feature enabled, a conversion should first be started. A high-to-low transition on  $\overrightarrow{\text{CONVST}}$  initiates a conversion. This puts the track-and-hold into hold mode and samples the analog input at this point. If the user does not want the AD7091R to enter power-down mode,  $\overrightarrow{\text{CONVST}}$  should be taken high before the end of the conversion. A conversion requires 650 ns to complete. When the conversion process is finished, the track-and-hold goes back to track mode. To prevent the BUSY indicator feature from becoming enabled, ensure that  $\overrightarrow{\text{CS}}$  is pulled high before the end of the conversion. The data is shifted out of the device as a 12-bit word under the control of SCLK and  $\overline{CS}$ . The MSB (Bit DB11) is clocked out on the falling edge of  $\overline{CS}$ . DB10 to DB0 are shifted out on the subsequent falling edges of SCLK. The 12<sup>th</sup> falling SCLK edge returns SDO to a high impedance state. After all the data is clocked out, pull  $\overline{CS}$  high again. SCLK should idle low in this mode to ensure that the MSB is not lost. Data is propagated on SCLK falling edges and is valid on both the rising and falling edges of the next SCLK. The timing diagram for this operation is shown in Figure 28.

If another conversion is required, pull  $\overline{\text{CONVST}}$  low and repeat the read cycle.





#### SOFTWARE RESET

The AD7091R requires the user to initiate a software reset when power is first applied. It should be noted that failure to apply the correct software reset command may result in a device malfunction.

To issue a software reset,

- 1. Start a conversion.
- 2. Read back the conversion result by pulling  $\overline{CS}$  low after the conversion is complete.
- 3. Between the second and eighth SCLK cycles, pull  $\overline{CS}$  high to short cycle the read operation.
- 4. At the end of the next conversion, the software reset is executed.

If using the on-chip internal reference, the user should wait until the reference capacitor is fully charged to meet the specified performance.

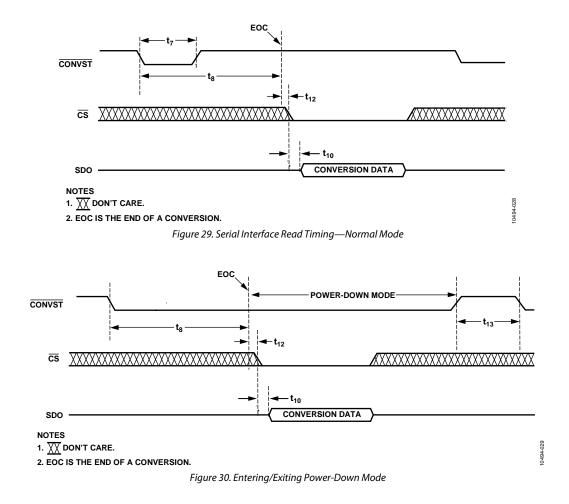
The timing diagram for this operation is shown in Figure 31.

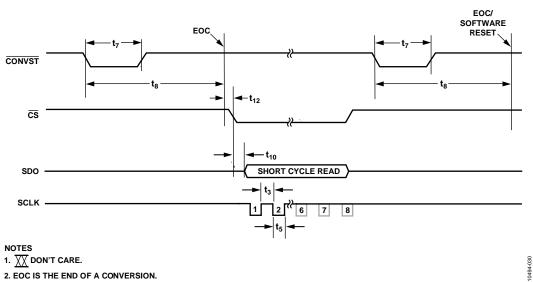
#### **INTERFACING WITH 8-/16-BIT SPI**

It is also possible to interface the AD7091R with a conventional 8-/16-bit SPI bus.

Performing conversions and reading results can be achieved by configuring the host SPI interface to 16 bits, which results in providing an additional four SCLK cycles to complete a conversion compared with the standard interface methods (see the With BUSY Indicator and Without BUSY Indicator sections). After the 13<sup>th</sup> SCLK falling edge with the BUSY indicator feature enabled or the 12<sup>th</sup> SCLK falling edge with the BUSY indicator feature disabled, SDO returns to a high impedance state. The additional four bits should be treated as don't cares by the host. All other timings are as outlined in Figure 27 and Figure 28, with t<sub>QUIET</sub> starting after the 16<sup>th</sup> SCLK cycle.

A software reset can be performed by configuring the SPI bus to eight bits and performing the operation outlined in the Software Reset section.

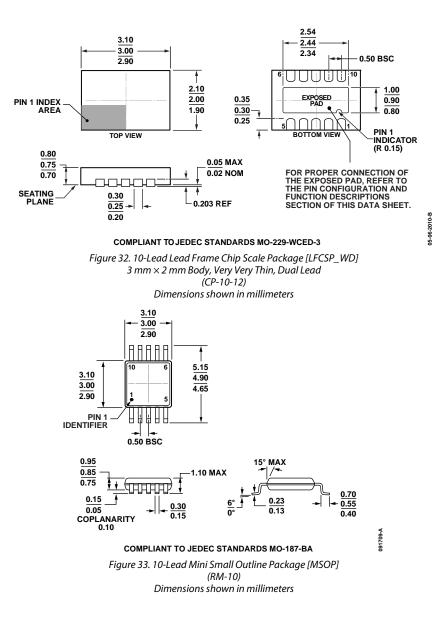




2. EOC IS THE END OF A CONVERSION.

Figure 31. Software Reset Timing

### **OUTLINE DIMENSIONS**



#### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Package Option	Branding
AD7091RBCPZ-RL	-40°C to +125°C	10-Lead Lead Frame Chip Scale Package [LFCSP_WD]	CP-10-12	C7P
AD7091RBCPZ-RL7	-40°C to +125°C	10-Lead Lead Frame Chip Scale Package [LFCSP_WD]	CP-10-12	C7P
AD7091RBRMZ	-40°C to +125°C	10-Lead Mini Small Outline Package [MSOP]	RM-10	DRQ
AD7091RBRMZ-RL7	-40°C to +125°C	10-Lead Mini Small Outline Package [MSOP]	RM-10	DRQ
EVAL-AD7091RSDZ		Evaluation Board		
EVAL-SDP-CB1Z		Evaluation Controller Board		

 $^{1}$  Z = RoHS Compliant Part.

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