

### **ZTLV431**

# 1.24V Cost effective shunt regulator

### **Description**

The ZTLV431 is a three terminal adjustable shunt regulator offering excellent temperature stability and output current handling capability up to 20mA. The output voltage may be set to any chosen voltage between 1.24 volts and 10 volts by selection of two external divider resistors.

#### **Features**

- Low voltage operation V<sub>REF</sub> = 1.24V
- Temperature range -40 to 125°C
- Reference voltage tolerance at 25°C
  - 1% ZTLV431A
- · Typical temperature drift
  - 4 mV (0°C to 70°C)
  - 6 mV (-40°C to 85°C)
  - 11mV (-40°C to 125°C
- 100µA minimum cathode current
- $0.25\Omega$  typical output impedance
- · Adjustable output voltage 1.24V to 10V

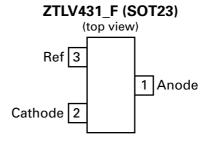
The ZTLV431 can be used as a replacement for zener diodes in many applications requiring an improvement in zener performance.

The ZTLV431 is available as standard as an A grade which has an initial tolerance of 1% and covers the -40°C to 125°C temperature range as standard.

### **Applications**

- · Opto-coupler linearization
- · Linear regulators
- Improved Zener
- · Variable reference

#### Pin connections



### **Ordering information**

Tol.	Order code	Package	Part mark	Status	Reel size (inches)	Tape width (mm)	Quantity per reel
1%	ZTLV431AFTA	SOT23	S1A	Active	7" (180mm)	8	3,000

### **Absolute maximum ratings**

Cathode voltage (V<sub>KA</sub>) 10V

Continuous cathode current ( $I_{KA}$ ) -20 to 20mA Reference input current range ( $I_{REF}$ ) -0.05 to 3mA Operating junction temperature -40 to 150°C Storage temperature -55 to 150°C

Operation above the absolute maximum rating may cause device failure. Operation at the absolute maximum ratings, for extended periods, may reduce device reliability.

Unless otherwise stated voltages specified are relative to the ANODE pin.

### Package thermal data

Package	$\Theta_{JA}$	P <sub>DIS</sub> T <sub>A</sub> =25°C
SOT23	380°C/W	330 mW
SOT23F	160°C/W	780 mW

### **Recommended operating conditions**

	Min.	Max.	Units
V <sub>KA</sub> cathode voltage	$V_{REF}$	10	V
I <sub>KA</sub> cathode current	0.1	15	mA
T <sub>A</sub> operating ambient temperature range	-40	125	°C

# Electrical characteristics (electrical characteristics over recommended operating conditions, $T_A = 25$ °C, $K_{KA} = V_{REF}$ , $I_{KA} = 10$ mA unless otherwise stated)

Symbol	Parameter	Conditions		Min.	Тур.	Max.	Units	
			ZTLV431A	1.228	1.24	1.252		
$V_{REF}$	Reference voltage	$T_A = -40 \text{ to } 85^{\circ}\text{C}$	ZTLV431A	1.215		1.265	V	
		$T_A = -40 \text{ to } 125^{\circ}\text{C}$	ZTLV431A	1.209		1.271		
	Deviation of reference	$T_A = 0 \text{ to } 70^{\circ}\text{C}$			4	12	mV	
V <sub>REF(dev)</sub>	voltage over full	$T_A = -40 \text{ to } 85^{\circ}\text{C}$			6	20		
	temperature range	$T_A = -40 \text{ to } 125^{\circ}\text{C}$		11	31	1		
	Ratio of change in		6V		-1.5	-2.7	mV/V	
$\frac{\Delta V_{REF}}{\Delta V_{KA}}$	reference voltage to the change in cathode voltage	$V_{KA}$ from $V_{REF}$ to $I_{KA} = 10$ mA	10V		-1.5	-2.7		
I <sub>REF</sub>	Reference input current	$I_{KA} = 10 \text{mA}, R_1 = 10 \text{k}\Omega, R_2 = OC$			0.1	0.5	μΑ	
	I <sub>REF</sub> deviation over full temperature range	I <sub>KA</sub> = 10mA,	$T_A = 0 \text{ to } 70^{\circ}\text{C}$		0.05	0.3	μA	
I <sub>REF(dev)</sub>		$R_1 = 10k\Omega$ ,	$T_A = -40 \text{ to } 85^{\circ}\text{C}$		0.1	0.4		
		$R_2 = OC$	$T_A = -40 \text{ to } 125^{\circ}\text{C}$		0.15	0.5		
I <sub>KMIN</sub>	Minimum cathode current for regulation	V <sub>KA</sub> = V <sub>REF</sub>	$T_A = -40 \text{ to } 125^{\circ}\text{C}$		55	100	μΑ	
I <sub>K(OFF)</sub>	Off-state current	V <sub>KA</sub> = 10V, V <sub>REF</sub> =0V			10	30	μΑ	
z <sub>KA</sub>	Dynamic output impedance	$V_{KA} = V_{REF}, f = < I_{K} = 0.1 \text{ to } 15\text{m/s}$			0.25	0.4	Ω	

Deviation of reference input voltage,  $V_{\text{DEV}}$ , is defined as the maximum variation of the reference input voltage over the full temperature range.

The average temperature coefficient of the reference input voltage,  $V_{\mbox{\scriptsize REF}}$  is defined as:

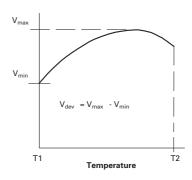
$$V_{REF}\left(\frac{ppm}{{}^{\circ}C}\right) = \frac{V_{DEV}x1000000}{V_{REF}(T_1 - T_2)}$$

The dynamic output impedance,  $Z_KA$ , is defined as:

$$Z_{KA} = \frac{\Delta V_K}{\Delta I_K}$$

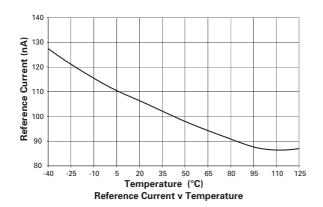
When the device is programmed with two external resistors, R1 and R2, (fig 2) , the dynamic output impedance of the overall circuit, Z', is defined as:

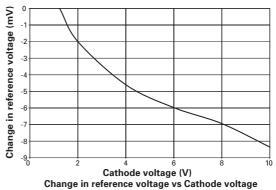
$$Z' = Z_{KA} x (+ \frac{R}{R})$$

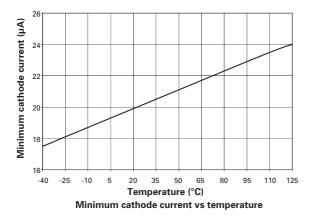


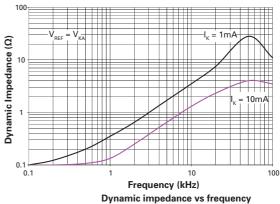


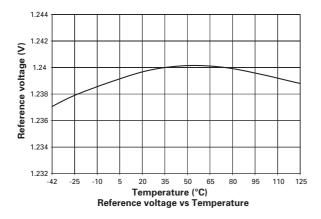
### **Typical characteristics**

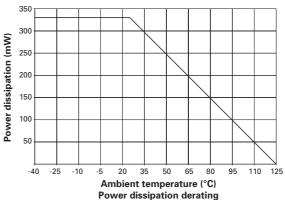






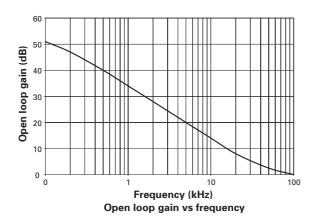


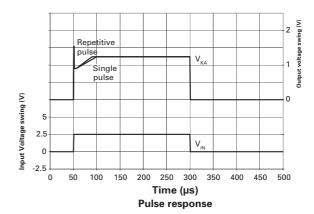


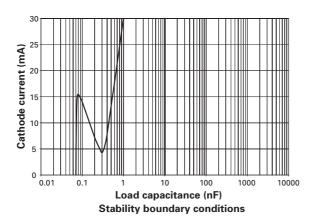




### **Typical characteristics**







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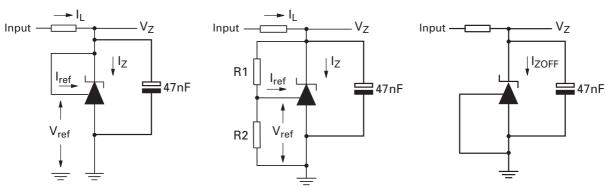


Fig 1 - Test circuit for  $V_Z = V_{ref}$ 

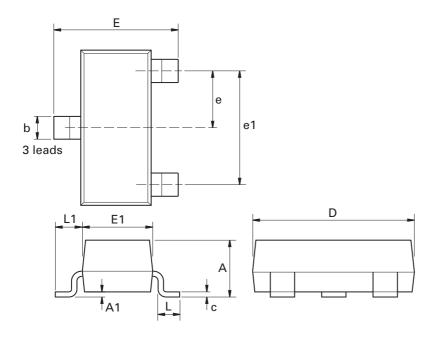
Fig 2 - Test circuit for  $V_Z > V_{ref}$ 

Fig 3 - Test circuit for for Off state current<sup>†</sup>

### Pin connections - preview status devices



## Package outline - SOT23



Dim.	Millimeters		Inches		Dim.	Millimeters		Inches	
	Min.	Мах.	Min.	Max.		Min.	Max.	Min.	Max.
Α	-	1.12	-	0.044	e1	1.90 NOM		0.075 NOM	
A1	0.01	0.10	0.0004	0.004	Е	2.10	2.64	0.083	0.104
b	0.30	0.50	0.012	0.020	E1	1.20	1.40	0.047	0.055
С	0.085	0.20	0.003	0.008	L	0.25	0.60	0.0098	0.0236
D	2.80	3.04	0.110	0.120	L1	0.45	0.62	0.018	0.024
е	0.95 NOM		0.037	NOM	-	-	-	-	-

Note: Controlling dimensions are in millimeters. Approximate dimensions are provided in inches

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