# 土80V Fault－Protected Full－Duplex RS－485 Transceiver 


#### Abstract

General Description The MAX13448E full－duplex RS－485 transceiver fea－ tures inputs and outputs fault protected up to $\pm 80 \mathrm{~V}$ （with respect to ground）．The device operates from a +3.0 V to +5.5 V supply and features true fail－safe cir－ cuitry，guaranteeing a logic－high receiver output when the receiver inputs are open or shorted．This enables all receiver outputs on a terminated bus to output logic－ high when all transmitters are disabled． The MAX13448E features a slew－rate limited driver that minimizes EMI and reduces reflections caused by improperly terminated cables，allowing error－free data transmission at data rates up to 500 kbps with a +5 V supply，and 250 kbps with a +3.3 V supply． The MAX13448E includes a hot－swap capability to elimi－ nate false transitions on the bus during power－up or hot insertion．The driver and receiver feature active－high and active－low enables，respectively，that can be connected together externally to serve as a direction control． The MAX13448E features an 1／8－unit load receiver input impedance，allowing up to 256 transceivers on the bus． All driver outputs are protected to $\pm 8 \mathrm{kV}$ ESD using the Human Body Model．The MAX13448E is available in a 14－pin SO package and operates over the extended $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ temperature range．


Applications
Industrial Control Systems
HVAC Control systems
Utility Meters
Motor Driver Control Systems

Features
－$\pm 80$ V Fault Protection on the RS－485 I／O Ports
－True Fail－Safe Receiver
－Hot－Swap Input Structure on DE
－ESD Protection on the RS－485 I／O Ports $\pm 8 \mathrm{kV}$ Human Body Model
－Slew－Rate Limiting Facilitates Error－Free Data Transmission
－1／8－Unit Load Allows Up to 256 Transceivers on the Bus
－-7 V to +12 V Common－Mode Input Voltage Range
－＋3．0V to＋5．5V Operating Supply Voltage
－Available in 14－Pin SO Package

Ordering Information

| PART | TEMP RANGE | PIN－PACKAGE |
| :---: | :--- | :--- |
| MAX13448EESD + | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 14 SO |

＋Denotes a lead－free package．

## Pin Configuration appears at end of data sheet．



For pricing，delivery，and ordering information，please contact Maxim Direct at 1－888－629－4642， or visit Maxim＇s website at www．maxim－ic．com．

## 土80V Fault-Protected Full-Duplex RS-485 Transceiver

## ABSOLUTE MAXIMUM RATINGS

(All voltages reference to GND.)
Supply Voltage (VCC).
...........................................+6V

Control Input Voltage ( $\overline{\mathrm{RE}}, \mathrm{DE}$ ). -0.3 V to $\left(\mathrm{V}_{\mathrm{CC}}+0.3 \mathrm{~V}\right)$
Driver Input Voltage (DI).............................-0.3V to (VCC +0.3 V )
Receiver Input Voltage (A, B (Note 1)) ................................ $\pm 80 \mathrm{~V}$
Driver Output Voltage (Y, Z (Note 1)) .................................. $\pm 80 \mathrm{~V}$
Receiver Output Voltage (RO).
-0.3 V to $(\mathrm{VCC}+0.3 \mathrm{~V})$
Short-Circuit Duration (RO, A, B) $\qquad$ Continuous

Continuous Power Dissipation $\left(\mathrm{T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}\right)$
14-Pin SO (derate $8.3 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ )................ 667 mW
Operating Temperature Range ........................... $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Junction Temperature
$+150^{\circ} \mathrm{C}$
Storage Temperature Range ............................. $65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Lead Temperature (soldering, 10s) ................................. $+300^{\circ} \mathrm{C}$

Note 1: If the RS-485 transmission lines are unterminated and a short to a voltage VSHT occurs at a remote point on the line, an active local driver (with DI switching) may see higher voltage than $V_{S H T}$ due to inductive kickback at the driver. Terminating the line with a resistor equal to its characteristic impedance minimizes this kickback effect.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS

$\left(\mathrm{V}_{C C}=+3.0\right.$ to $+5.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $T_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C}=+3.3 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Notes 2,3$)$

| PARAMETER | SYMBOL | CONDITION | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VCC Supply Voltage Range | VCC |  | 3.0 |  | 5.5 | V |
| Supply Current | IQ | No load, DE, DI, $\overline{\mathrm{RE}}=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{C C}=3.3 \mathrm{~V}$ |  |  | 15 | mA |
|  |  | No load, DE, DI, $\overline{\mathrm{RE}}=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{C C}=5 \mathrm{~V}$ |  |  | 15 |  |
| Supply Current in Shutdown Mode | ISHDN | $\mathrm{DE}=\mathrm{GND}, \overline{\mathrm{RE}}=\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{C C}=3.3 \mathrm{~V}$ |  |  | 100 | $\mu \mathrm{A}$ |
|  |  | $D E=G N D, \overline{R E}=V_{C C}, V_{C C}=5 \mathrm{~V}$ |  |  | 100 |  |
| Supply Current with Output Shorted to $\pm 60 \mathrm{~V}$ | ISHRT | $\mathrm{DE}=\mathrm{GND}, \overline{\mathrm{RE}}=\mathrm{GND}$, short to +60 V |  |  | 15 | mA |
|  |  | DE $=$ GND, $\overline{\mathrm{RE}}=\mathrm{GND}$, short to -60V |  |  | 15 |  |
| DRIVER |  |  |  |  |  |  |
| Differential Driver Output | VOD | $R_{L}=100 \Omega$, Figure 1 | 2 |  | VCC | V |
|  |  | $R L=54 \Omega$, Figure 1 | 1.5 |  | VCC |  |
| Change in Magnitude of Differential Output Voltage | $\Delta \mathrm{V}_{\mathrm{OD}}$ | $R_{L}=100 \Omega$ or $54 \Omega$, Figure 1 (Note 4) | -0.2 |  | 0.2 | V |
| Driver Common-Mode Output Voltage | Voc | RL $=100 \Omega$ or $54 \Omega$, Figure 1 |  | VCC/2 | 3 | V |
| Change in Magnitude of Common-Mode Voltage | $\Delta \mathrm{VOC}$ | RL $=100 \Omega$ or $54 \Omega$, Figure 1 (Note 4) | -0.2 |  | +0.2 | V |
| Driver Short-Circuit Output Current | IOSD | $\mathrm{DI}=$ low, $\mathrm{OV} \leq \mathrm{V}_{\mathrm{Y}}$ or $\mathrm{V}_{\mathrm{Z}} \leq+12 \mathrm{~V}$ |  |  | +250 | mA |
|  |  | $\mathrm{DI}=$ high, $-7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{Y}}$ or $\mathrm{V}_{Z} \leq \mathrm{V}_{\mathrm{CC}}$ ( Note 5) | -250 |  |  |  |
| Driver Short-Circuit Foldback Output Current | IOSDF | $\mathrm{DI}=$ low, ( $\left.\mathrm{V}_{C C}-1 \mathrm{~V}\right) \leq \mathrm{V}_{Y}$ or $\mathrm{V}_{Z} \leq+12 \mathrm{~V}$ | +10 |  |  | mA |
|  |  | $\mathrm{DI}=$ high, $-7 \mathrm{~V} \leq \mathrm{V}_{Y}$ or $\mathrm{V}_{Z} \leq+1 \mathrm{~V}$ |  |  | -10 |  |
| Driver-Limit Short-Circuit Foldback Output Current | IOSDL | $V_{Y}$ or $V_{Z} \geq+22 \mathrm{~V}, \mathrm{R}_{L}=100 \Omega$ |  |  | +6 | mA |
|  |  | $V_{Y}$ or $V_{Z} \leq-13 V, R_{L}=100 \Omega$ | -6 |  |  |  |
| Driver Input High Voltage | $V_{\text {DIH }}$ |  | 2 |  |  | V |
| Driver Input Low Voltage | V DIL |  |  |  | 0.8 | V |
| Driver Input Current | IDIN |  | -1 |  | +1 | $\mu \mathrm{A}$ |

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## ELECTRICAL CHARACTERISTICS (continued)

$\left(\mathrm{V}_{C C}=+3.0\right.$ to $+5.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$. $)($ Notes 2,3$)$


## SWITCHING CHARACTERISTICS (VCC = +3.3V $\pm 10 \%$ )

( $T_{A}=T_{\text {MIN }}$ to $T_{M A X}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C}=+3.3 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |  |
| Driver Differential Propagation Delay | $\begin{aligned} & \text { tDPLH, } \\ & \text { tDPHL } \end{aligned}$ | $R_{L}=54 \Omega, C L=50 p F$, Figures 2 and 3 |  | 700 | 1500 | ns |
| Driver Differential Output Transition Time | tLH, thl | $R_{L}=54 \Omega, C L=50 p F$, Figures 2 and 3 | 250 |  | 1200 | ns |
| Differential Driver Output Skew | tDSKEW | $\mathrm{R}_{\mathrm{L}}=54 \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \text { tDSKEW }=[\mathrm{t} \text { DPLH }-$ tDPHL], Figures 2 and 3 |  | 150 | 200 | ns |
| Maximum Data Rate | $\mathrm{f}_{\text {MAX }}$ |  | 250 |  |  | kbps |
| Driver Enable Time to Output High | tDZH | $\mathrm{R}_{\mathrm{L}}=500 \Omega, C_{L}=50 \mathrm{pF}$, Figure 4 |  |  | 2000 | ns |

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SWITCHING CHARACTERISTICS (Vcc $=+3.3 \mathrm{~V} \pm 10 \%$ ) (continued)
( $T_{A}=T_{M I N}$ to $T_{M A X}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C}=+3.3 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Disable Time from Output High | tDHZ | $R_{L}=500 \Omega, C_{L}=50 p F$, Figure 4 |  | 1000 | ns |
| Driver Enable Time from Shutdown to Output High | tDZH(SHDN) | $R_{L}=500 \Omega, C_{L}=50 p F$, Figure 4 |  | 8 | $\mu \mathrm{s}$ |
| Driver Enable Time to Output Low | tDZL | $\mathrm{R}_{\mathrm{L}}=500 \Omega, C_{L}=50 \mathrm{pF}$, Figure 5 |  | 1500 | ns |
| Driver Disable Time from Output Low | tDLZ | $R_{L}=500 \Omega, C_{L}=50 p F$, Figure 5 |  | 2000 | ns |
| Driver Enable Time from Shutdown to Output Low | tDZL(SHDN) | $R_{L}=500 \Omega, C_{L}=50 p F$, Figure 5 |  | 8 | $\mu \mathrm{s}$ |
| Driver Time to Shutdown | tSHDN | $R_{L}=500 \Omega, C_{L}=50 p F$ |  | 12 | $\mu \mathrm{s}$ |
| RECEIVER |  |  |  |  |  |
| Receiver Propagation Delay | tRPLH, <br> tRPHL | $C_{L}=20 \mathrm{pF}, \mathrm{~V}_{\mathrm{ID}}=2 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=0 \mathrm{~V} \text {, }$ Figure 6 |  | 2000 | ns |
| Receiver Output Skew | trSKEW | $\begin{aligned} & C_{L}=20 \mathrm{pF}, \text { tRSKEW }=\left[\text { tRPLH }-t_{\text {RPHL }}\right], \\ & \text { Figure } 6 \end{aligned}$ |  | 200 | ns |
| Receiver Enable Time to Output High | tRZH | $R_{L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 1000 | ns |
| Receiver Disable Time from Output High | trHz | $R_{L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 150 | ns |
| Receiver Wake Time from Shutdown | trWAKE | $R \mathrm{~L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 5 | $\mu \mathrm{s}$ |
| Receiver Enable Time to Output Low | tRZL | $R \mathrm{~L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 1000 | ns |
| Receiver Disable Time from Output Low | tRLZ | $R_{L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 150 | ns |
| Receiver Time to Shutdown | tSHDN | $R_{L}=500 \Omega, C_{L}=50 p F$ |  | 200 | ns |

## SWITCHING CHARACTERISTICS (Vcc $=+5 \mathrm{~V} \pm 10 \%$ )

( $\mathrm{T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{V}_{\mathrm{CC}}=+5 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |  |
| Driver Differential Propagation Delay | tDPLH, tDPHL | $R_{L}=54 \Omega, C L=50 p F$, Figure 3 |  |  | 800 | ns |
| Driver Differential Output Transition Time | tLH, thl | $R_{L}=54 \Omega, C L=50 p F$, Figure 3 | 100 |  | 1200 | ns |
| Differential Driver Output Skew | tDSKEW | $\mathrm{R}_{\mathrm{L}}=54 \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \text { tDSKEW }=[\mathrm{t} \text { DPLH }-$ tDPHL], Figure 3 |  |  | 200 | ns |
| Maximum Data Rate | $f_{\text {max }}$ |  | 500 |  |  | kbps |

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## SWITCHING CHARACTERISTICS (VcC = +5V $\pm 10 \%$ ) (continued)

( $T_{A}=T_{\text {MIN }}$ to $T_{M A X}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C}=+5 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Enable Time to Output High | tDZH | $\mathrm{R}_{\mathrm{L}}=500 \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$, Figure 4 |  | 1500 | ns |
| Driver Disable Time from Output High | tDHZ | $R_{L}=500 \Omega, C L=50 p F$, Figure 4 |  | 1000 | ns |
| Driver Enable Time from Shutdown to Output High | tDZH(SHDN) | $R \mathrm{~L}=500 \Omega, \mathrm{CL}_{\mathrm{L}}=50 \mathrm{pF}$, Figure 4 |  | 8 | $\mu \mathrm{s}$ |
| Driver Enable Time to Output Low | tDZL | $R_{L}=500 \Omega, C_{L}=50 p F$, Figure 5 |  | 1000 | ns |
| Driver Disable Time from Output Low | tDLZ | $R_{L}=500 \Omega, C L=50 p F$, Figure 5 |  | 2 | $\mu \mathrm{s}$ |
| Driver Enable Time from Shutdown to Output Low | tDZL(SHDN) | $R \mathrm{~L}=500 \Omega, C_{L}=50 \mathrm{pF}$, Figure 5 |  | 8 | $\mu \mathrm{s}$ |
| Driver Time to Shutdown | tSHDN | $R_{L}=500 \Omega, C_{L}=50 p F$ |  | 12 | $\mu \mathrm{s}$ |
| RECEIVER |  |  |  |  |  |
| Receiver Propagation Delay | tRPLH, tRPHL | $C_{L}=20 \mathrm{pF}, \mathrm{~V}_{\mathrm{ID}}=2 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=0 \mathrm{~V},$ <br> Figure 6 |  | 2000 | ns |
| Receiver Output Skew | tRSKEW | $\mathrm{CL}_{\mathrm{L}}=20 \mathrm{pF}, \text { tRSKEW }=\left[\mathrm{tRPLH}-\mathrm{t}_{\text {RPHL }}\right] \text {, }$ <br> Figure 6 |  | 200 | ns |
| Receiver Enable Time to Output High | tRZH | $R_{L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 1000 | ns |
| Receiver Disable Time from Output High | tRHZ | $R \mathrm{~L}=1 \mathrm{k} \Omega, C \mathrm{~L}=20 \mathrm{pF}$, Figure 7 |  | 150 | ns |
| Receiver Wake Time from Shutdown | trWAKE | $R \mathrm{~L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 8 | $\mu \mathrm{S}$ |
| Receiver Enable Time to Output Low | tRZL | $R_{L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 1000 | ns |
| Receiver Disable Time from Output Low | tRLZ | $R_{L}=1 \mathrm{k} \Omega, C_{L}=20 \mathrm{pF}$, Figure 7 |  | 150 | ns |
| Receiver Time to Shutdown | tSHDN | $\mathrm{R}_{\mathrm{L}}=500 \Omega, \mathrm{CL}_{\mathrm{L}}=50 \mathrm{pF}$ |  | 150 | ns |

Note 2: Parameters are $100 \%$ production tested at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. Limits over temperature are guaranteed by design.
Note 3: All currents into the device are positive. All currents out of the device are negative. All voltages are referenced to device ground, unless otherwise noted.
Note 4: $\Delta \mathrm{V}_{O D}$ and $\Delta \mathrm{V}_{\mathrm{OC}}$ are the changes in $\mathrm{V}_{O D}$ and $\mathrm{V}_{O C}$, respectively, when the D input changes state.
Note 5: The short-circuit output current applies to peak current just prior to foldback current limiting. The short-circuit foldback output current applies during current limiting to allow a recover from bus contention.

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## Typical Operating Characteristics (continued)

$\left(\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted. $)$



DRIVER PROPAGATION DELAY
vs. TEMPERATURE


RECEIVER PROPAGATION DELAY (500kbsp)


RECEIVER PROPAGATION DELAY
vs. TEMPERATURE


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| PIN | NAME | FUNCTION |
| :---: | :---: | :---: |
| 1，8， 13 | N．C． | No Connection．Not internally connected．Connect N．C．to GND or leave it unconnected． |
| 2 | RO | Receiver Output．If receiver is enabled and（ $A-B) \geq-50 \mathrm{mV}, \mathrm{RO}=$ high；if $(A-B) \geq-200 \mathrm{mV}, \mathrm{RO}=$ low． |
| 3 | $\overline{\mathrm{RE}}$ | Receiver Output Enable．Drive $\overline{\mathrm{RE}}$ low to enable RO；RO is high impedance when $\overline{\mathrm{RE}}$ is high．Drive $\overline{R E}$ high and DE low to enter low－power shutdown mode． |
| 4 | DE | Driver Output Enable．Drive DE high to enable the driver outputs．Drive DE low to put the outputs in high impedance．Drive $\overline{\mathrm{RE}}$ high and $D E$ low to enter low－power shutdown mode． |
| 5 | DI | Driver Input．Drive DI low to force the noninverting output low and the inverting output high．Drive DI high to force the noninverting output high and the inverting output low． |
| 6， 7 | GND | Ground |
| 9 | Y | Noninverting Driver Output |
| 10 | Z | Inverting Driver Output |
| 11 | B | Inverting Receiver Input |
| 12 | A | Noninverting Receiver Input |
| 14 | VCC | Positive Supply． $\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}$ to +5.5 V ．Bypass $\mathrm{V}_{\mathrm{CC}}$ to GND with a $1 \mu \mathrm{~F}$ ceramic capacitor as close to $\mathrm{V}_{\mathrm{CC}}$ as possible．Typical $\mathrm{V}_{\mathrm{CC}}$ values are at $\mathrm{V}_{C C}=+3.3 \mathrm{~V}$ and $\mathrm{V}_{\mathrm{CC}}=+5.0 \mathrm{~V}$ ． |



Figure 1．Driver DC Test Load


Figure 2．Driver Timing Test Circuit


Figure 3．Driver Propagation Delays

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Figure 4. Driver Enable and Disable Times (tDHZ, $\left.t_{D Z H}, t_{D Z H}(S H D N)\right)$


Figure 5. Driver Enable and Disable Times (tDLZ, $t_{D Z L}, t_{D Z L(S H D N)) ~}^{\text {) }}$

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Figure 6. Receiver Propagation Delays


Figure 7. Receiver Enable and Disable Times

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## Detailed Description

The MAX13448E $\pm 80 \mathrm{~V}$ fault－protected RS－485／RS－422 transceiver contains one driver and one receiver．This device features fail－safe circuitry，guaranteeing a logic－ high receiver output when the receiver inputs are open or shorted，or when they are connected to a terminated transmission line with all drivers disabled．The device has a hot－swap input structure that prevents distur－ bances on the differential signal lines when a circuit board is plugged into a hot backplane．All receiver inputs and driver outputs are protected to $\pm 8 \mathrm{kV}$ ESD using the Human Body Model．The MAX13448E features a reduced slew－rate driver that minimizes EMI and reduces reflections caused by improperly terminated cables，allowing error－free data transmis－ sion up to 500kbps．

## Driver

The driver accepts a single－ended，logic－level input （DI）and converts it to a differential，RS－485／RS－422 level output（ $A$ and $B$ ）．Deasserting the driver enable places the driver outputs（ $A$ and $B$ ）into a high－imped－ ance state．

## Receiver

The receiver accepts a differential，RS－485／RS－422 level input（ $A$ and $B$ ），and translates it to a single－ ended，logic－level output（RO）．Deasserting the receiv－ er enable places the receiver outputs（RO）into a high－impedance state（see Table 1）．

Low－Power Shutdown
Low－power shutdown is initiated by bringing DE Iow and RE high．In shutdown，the device draws a maxi－ mum of $100 \mu \mathrm{~A}$ of supply current．
The device is guaranteed to not enter shutdown if $D E$ is low and RE is high for $1 \mu \mathrm{~s}$ ．If the inputs are in this state for at least 1 ms ，the device is guaranteed to enter shut－ down．In the shutdown state，the driver outputs（A and $B$ ）as well as the receiver output（ RO ）are in a high－ impedance state．

## $\pm 80 V$ Fault Protection

In certain applications，such as industrial control，driver outputs and receiver inputs of an RS－485 device some－ times experience common－mode voltages in excess of the -7 V to +12 V range specified in the EIA／TIA－485 standard．In these applications，ordinary RS－485 devices（typical absolute maximum ratings of -8 V to +12.5 V ）may experience damage without the addition of external protection devices．

Table 1．Function Table

| TRANSMITTING |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| INPUT |  |  | OUTPUT |  |
| $\overline{\mathrm{RE}}$ | DE | DI | $Z$ | Y |
| X | 1 | 0 | 1 | 0 |
| $X$ | 1 | 1 | 0 | 1 |
| 0 | 0 | $X$ | High <br> Impedance | High <br> Impedance |
| 1 | 0 | $X$ | High Impedance（Shutdown） |  |
| INPUT |  |  |  |  |
| $\overline{R E}$ | DE | $\mathrm{A}-\mathrm{B}$ | OUTPUT |  |
| 0 | $X$ | -50 mV | 1 |  |
| 0 | $X$ | -200 mV | 0 |  |
| 1 | 1 | $X$ | Disabled |  |
| 1 | 0 | $X$ | High Impedance（Shutdown） |  |

$X=$ Don＇t care；shutdown mode，driver，and receiver outputs are high impedance．

To reduce system complexity and the need for external protection，the driver outputs and receiver inputs of the MAX13448E withstand voltage faults of up to $\pm 80 \mathrm{~V}$ with respect to ground without damage（see the Absolute Maximum Ratings section，Note 1）．Protection is guar－ anteed regardless of whether the device is active，in shutdown，or without power．Certain parasitic effects present while driving an unterminated cable may cause the voltage seen at driver outputs to exceed the absolute maximum limit，while the DI input is switched during a $\pm 80 \mathrm{~V}$ fault on the A or B input．Therefore， a termination resistor is recommend in order to maximize the overvoltage fault protection while the DI input is being switched．If the DI input does not change state while the fault voltage is present，the MAX13448E will withstand up the $\pm 80 \mathrm{~V}$ on the RS－485 inputs，regard－ less of the presence of a termination resistor．While the MAX13448E is not damaged by up to $\pm 80 \mathrm{~V}$ common－ mode voltages，the RO，$Y$ ，and $Z$ outputs will be in an indeterminate state if the common－mode voltage exceeds -7 V to +12 V ．

True Fail－Safe
The MAX13448E guarantees a logic－high receiver out－ put when the receiver inputs are shorted or open，or when they are connected to a terminated transmission line with all drivers disabled．This is done by setting the

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Figure 8a. Human Body ESD Test Model
receiver threshold between -50 mV and -200 mV . If the differential receiver input voltage ( $A-B$ ) is greater than or equal to $-50 \mathrm{mV}, \mathrm{RO}$ is logic-high. If $\mathrm{A}-\mathrm{B}$ is less than or equal to $-200 \mathrm{mV}, \mathrm{RO}$ is logic-low. In the case of a terminated bus with all transmitters disabled, the receiver's differential input voltage is pulled to OV by the termination. With the receiver thresholds of the MAX13448E, this results in a logic-high with a 50 mV minimum noise margin. The -50 mV to -200 mV threshold complies with the $\pm 200 \mathrm{mV}$ EIA/TIA-485 standard.

## 士8KV ESD Protection

As with all Maxim devices, ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver outputs and receiver inputs of the MAX13448E have extra protection against static electricity. Maxim's engineers have developed state-of-theart structures to protect these pins against ESD of $\pm 8 \mathrm{kV}$ without damage. The ESD structures withstand high ESD in all states: normal operation, shutdown, and powered down. After an ESD event, the MAX13448E keeps working without latchup or damage. ESD protection can be tested in various ways. The transmitter outputs and receiver inputs of the MAX13448E are characterized for protection to the following limits:

- $\pm 8 \mathrm{kV}$ using the Human Body Model


## ESD Test Conditions

ESD performance depends on a variety of conditions. Contact Maxim for a reliability report that documents test setup, test methodology, and test results.

## Human Body Model

 Figure 8a shows the Human Body Model, and Figure 8b shows the current waveform it generates when discharged into a low impedance. This model consists of a

Figure 8b. Human Body Current Waveform

100pF capacitor charged to the ESD voltage of interest, which is then discharged into the test device through a $1.5 \mathrm{k} \Omega$ resistor.

## Driver Output Protection

Two mechanisms prevent excessive output current and power dissipation caused by faults or by bus contention. The first, a foldback current limit on the output stage, provides immediate protection against short circuits over the whole common-mode voltage range (see the Typical Operating Characteristics). The second, a thermal-shutdown circuit, forces the driver outputs into a high-impedance state if the die temperature exceeds $+160^{\circ} \mathrm{C}$ (typ).

## Hot-Swap Capability

Hot-Swap Inputs
When circuit boards are inserted into a powered backplane, disturbances to the data bus can lead to data errors. Upon initial circuit-board insertion, the data communication processor undergoes its own power-up sequence. During this period, the processor's logicoutput drivers are high impedance and are unable to drive the DE input of the device to a defined logic level. Leakage currents up to $\pm 10 \mu \mathrm{~A}$ from the high-impedance state of the processor's logic drivers could cause standard CMOS enable inputs of a transceiver to drift to an incorrect logic level. Additionally, parasitic circuitboard capacitance could cause coupling of VCC or GND to the enable inputs. Without the hot-swap capability, these factors could improperly enable the transceiver's driver or receiver.
When VCc rises, an internal pulldown circuit holds DE low. After the initial power-up sequence, the pulldown circuit becomes transparent, resetting the hot-swap tolerable input.

# 土80V Fault－Protected Full－Duplex RS－485 Transceiver 



Figure 9．Simplified Structure of the Driver Enable Pin（DE）
Hot－Swap Input Circuitry The enable inputs feature hot－swap capability．At the input there are two NMOS devices，M1 and M2（Figure 9）．When VCC ramps from zero，an internal $7 \mu \mathrm{~s}$ timer turns on M2 and sets the SR latch that also turns on M1． Transistor M2，a 1.5 mA current sink，and M1，a $100 \mu \mathrm{~A}$ current sink，pull DE to GND through a $5 k \Omega$ resistor．M2 is designed to pull $D E$ to the disabled state against an external parasitic capacitance up to 100 pF that can drive DE high．After 7 ss ，the timer deactivates M2 while M1 remains on，holding DE low against three－state leak－ ages that can drive DE high．M1 remains on until an external source overcomes the required input current． At this time，the SR latch resets and M1 turns off．When M1 turns off，DE reverts to a standard，high－impedance CMOS input．

## Applications Information

## 256 Transceivers on the Bus

 The RS－485 standard specifies the load each receiver places on the bus in terms of unit loads．An RS－485 compliant transmitter can drive 32 one－unit loads when used with a $120 \Omega$ cable that is terminated on both ends over a common－mode range of -7 V to +12 V ．TheMAX13448E is specified as $1 / 8$ unit loads．This means a compliant transmitter can drive up to 256 MAX13448E devices．Reducing the common mode and／or changing the characteristic impedance of the cable changes the maximum number of receivers that can be used．Refer to the TIA／EIA－485 specification for further details．

Proper Termination and Cabling／Wiring Configurations
When the data rates for RS－485 are high relative to its cable lengths，the system is subject to proper transmis－ sion line design．In most cases，a single，controlled－ impedance cable or trace should be used and should be properly terminated on both ends with the characteristic impedance of the cable／trace．RS－485 transceivers should be connected to the cable／traces with minimum length wires to prevent stubs．Star configurations and improperly terminated cables can cause data loss．Refer to the Applications section of the Maxim website or to TIA／EIA publication TSB89 for further information．

## Reduced EMI and Reflections

The MAX13448E features reduced slew－rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables，allowing error－free data transmission up to 500 kbps ．

## Line Length

The Telecommunications Industry Association（TIA） publishes the document TSB－89：Application Guidelines for TIA／EIA－485－A that is a good reference for determining maximum data rate vs．line length．

## Typical Applications

The MAX13448E transceivers are designed for bidirec－ tional data communications on multipoint bus transmis－ sion lines．Figure 10 shows a typical network application circuit．To minimize reflections，terminate the line at both ends in its characteristic impedance，and keep stub lengths off the main line as short as possible．

## 土80V Fault-Protected Full-Duplex RS-485 Transceiver



Figure 10. Typical Full-Duplex RS-485 Network

Pin Configuration


Chip Information
PROCESS: BiCMOS

## Package Information

For the latest package outline information and land patterns, go to www.maxim-ic.com/packages.

| PACKAGE TYPE | PACKAGE CODE | DOCUMENT NO. |
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