# Quad Bus LVDS Driver with Flow-Through Pinout 

## General Description

The MAX9129 is a quad bus low-voltage differential signaling (BLVDS) driver with flow-through pinout. This device is designed to drive a heavily loaded multipoint bus with controlled transition times ( $1 \mathrm{~ns} 0 \%$ to $100 \%$ minimum) for reduced reflections. The MAX9129 accepts four LVTTL/LVCMOS input levels and translates them to output levels of 250 mV to 450 mV (standard LVDS levels) into a $27 \Omega$ load at speeds up to 200Mbps ( 100 MHz ).
The power-on reset ensures that all four outputs are disabled and high impedance during power up and power down. The outputs can be set to high impedance by two enable inputs, EN and EN, thus dropping the device to a low-power state of 11 mW . The enables are common to all four drivers. The flow-through pinout simplifies PC board layout and reduces crosstalk by keeping the LVTTL/LVCMOS inputs and BLVDS outputs separated.
The MAX9129 operates from a single +3.3 V supply and is specified for operation from $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$. It is available in 16-pin QFN and TSSOP packages. Refer to the MAX9121 data sheet for a quad LVDS line receiver with flow-through pinout.

## Applications

Cell Phone Base Stations
Add/Drop Muxes
Digital Cross-Connects
DSLAMs
Network Switches/Routers
Backplane Interconnect
Clock Distribution

Features

- Drive LVDS Levels into a $27 \Omega$ Load
- 1ns (0\% to 100\%) Minimum Transition Time Reduces Reflections
- Guaranteed 200Mbps (100MHz) Data Rate
- Enable Pins for High-Impedance Output
- High-Impedance Outputs when Powered Off
- Glitch-Free Power-Up and Power-Down
- Hot Swappable
- Flow-Through Pinout
- Available in Tiny QFN Package (50\% Smaller than TSSOP)
- Single +3.3V Supply

Ordering Information

| PART | TEMP. RANGE | PIN-PACKAGE |
| :--- | :--- | :--- |
| MAX9129EGE | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 16 QFN |
| MAX9129EUE | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 16 TSSOP |

Functional Diagram appears at end of data sheet. Pin Configurations appear at end of data sheet.

Typical Applications Circuit


# Quad Bus LVDS Driver with Flow-Through Pinout 

## ABSOLUTE MAXIMUM RATINGS

| VCc to GND |  |
| :---: | :---: |
| IN_, EN, $\overline{\text { EN }}$ to GND. | (VCc + 0.3V) |
| OUT_+, OUT_- to GND....................................-0.3V to +4.0V |  |
| Short-Circuit Duration (OUT_+, OUT_-) .....................Continuous Continuous Power Dissipation ( $\mathrm{T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}$ ) |  |
|  |  |
| 16-Pin QFN (derate $18.5 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) | 1481 mW |
| 16-Pin TSSOP (derate $9.4 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) | 755 mW |

Storage Temperature Range .............................. $65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Maximum Junction Temperature ..................................... $+150^{\circ} \mathrm{C}$
Operating Temperature Range ........................... $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ ESD Protection

Human Body Model, OUT_+, OUT_- .................................. $\pm 8 \mathrm{kV}$
Lead Temperature (soldering, 10s) ................................. $300^{\circ} \mathrm{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## DC ELECTRICAL CHARACTERISTICS

$\left(\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}\right.$ to $+3.6 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=27 \Omega \pm 1 \%, \mathrm{EN}=$ high, $\overline{\mathrm{EN}}=$ low, $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{V}_{\mathrm{CC}}$ $=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Notes 1, 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BLVDS OUTPUTS (OUT_+, OUT_-) |  |  |  |  |  |  |
| Differential Output Voltage | Vod | Figure 1 | 250 | 371 | 450 | mV |
| Change in Magnitude of VOD Between Complementary Output States | $\Delta \mathrm{VOD}$ | Figure 1 |  | 1 | 25 | mV |
| Offset Voltage | Vos | Figure 1 | 1.125 | 1.29 | 1.375 | V |
| Change in Magnitude of $\mathrm{V}_{\mathrm{OS}}$ <br> Between Complementary Output <br> States | $\Delta \mathrm{V}$ OS | Figure 1 |  | 5 | 25 | mV |
| Output High Voltage | VOH |  |  | 1.465 | 1.6 | V |
| Output Low Voltage | VOL |  | 0.90 | 1.085 |  | V |
| Differential Output Short-Circuit Current | IOSD | $V_{O D}=0$ |  |  | 20 | mA |
| Output Short-Circuit Current | Ios | $\begin{aligned} & \text { OUT_+ }=0 \text { at } I N_{-}=V_{C C} \text { or } \\ & \text { OUT-- }=0 \text { at } \mathrm{IN}_{-}=0 \end{aligned}$ |  |  | -20 | mA |
| Output High-Impedance Current | Ioz | Disabled, OUT_+ = 0 or $\mathrm{V}_{\mathrm{CC}}$, OUT_- $=0$ or Vcc | -1 |  | 1 | $\mu \mathrm{A}$ |
| Power-Off Output Current | IOFF | $\begin{aligned} & \mathrm{V}_{\mathrm{CC}}=0 \text { or open, } \mathrm{EN}=\overline{\mathrm{EN}}=\mathbb{I N}=0, \\ & \text { OUT_+ }=0 \text { or } 3.6 \mathrm{~V}, \mathrm{OUT}_{-}-=0 \text { or } 3.6 \mathrm{~V} \end{aligned}$ | -1 |  | 1 | $\mu \mathrm{A}$ |
| Output Capacitance | Cout | Capacitance from OUT_+ or OUT_- to GND |  | 4.3 |  | pF |
| INPUTS (IN_, EN, $\overline{\text { EN }}$ ) |  |  |  |  |  |  |
| High-Level Input Voltage | $\mathrm{V}_{\mathrm{IH}}$ |  | 2.0 |  | VCC | V |
| Low-Level Input Voltage | $\mathrm{V}_{\text {IL }}$ |  | GND |  | 0.8 | V |
| Input Current | IIN | IN_, EN, $\overline{E N}=0$ or VCC | -15 |  | 15 | $\mu \mathrm{A}$ |
| SUPPLY CURRENT |  |  |  |  |  |  |
| Supply Current | Icc | $\mathrm{R}_{\mathrm{L}}=27 \Omega, 1 \mathrm{~N}_{-}=\mathrm{V}_{C C}$ or 0 for all channels |  | 58 | 70 | mA |
| Disabled Supply Current | ICCZ | Disabled |  | 3.2 | 5 | mA |

# Quad Bus LVDS Driver with Flow-Through Pinout 

## AC ELECTRICAL CHARACTERISTICS

( $\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}$ to $+3.6 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=27 \Omega \pm 1 \%, \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}, \mathrm{EN}=$ high, $\overline{\mathrm{EN}}=$ low, $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Notes 3, 4, 5)

| PARAMETER | SYMBOL | CONDITIONS |  | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Differential Propagation Delay High to Low | tPHLD | Figures 2 and 3 |  | 1.0 | 1.98 | 3.0 | ns |
| Differential Propagation Delay Low to High | tPLHD | Figures 2 and 3 |  | 1.0 | 1.92 | 3.0 | ns |
| Differential Pulse Skew (Note 6) | tSKD1 | Figures 2 and 3 |  |  |  | 300 | ps |
| Differential Channel-to-Channel Skew (Note 7) | tSKD2 | Figures 2 and 3 |  |  |  | 450 | ps |
| Differential Part-to-Part Skew (Note 8) | tSKD3 | Figures 2 and 3 |  |  |  | 1.2 | ns |
| Differential Part-to-Part Skew (Note 9) | tSKD4 | Figures 2 and 3 |  |  |  | 2.0 | ns |
| Rise Time | ttil | Figures 2 and 3 | MAX9129EGE | 0.60 | 1.19 | 1.55 | ns |
|  |  |  | MAX9129EUE | 0.60 | 1.09 | 1.40 |  |
| Fall Time | tTHL | Figures 2 and 3 | MAX9129EGE | 0.60 | 1.12 | 1.55 | ns |
|  |  |  | MAX9129EUE | 0.60 | 1.02 | 1.40 |  |
| Disable Time High to Z | tphz | Figures 4 and 5 |  |  |  | 8 | ns |
| Disable Time Low to Z | tplZ | Figures 4 and 5 |  |  |  | 8 | ns |
| Enable Time Z to High | tPZH | Figures 4 and 5 |  |  |  | 10 | ns |
| Enable Time Z to Low | tpZL | Figures 4 and 5 |  |  |  | 10 | ns |
| Maximum Operating Frequency (Note 10) | $f_{\text {max }}$ | Figure 2 |  | 100 |  |  | MHz |

Note 1: Maximum and minimum limits over temperature are guaranteed by design and characterization. Devices are 100\% tested at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.
Note 2: Current into the device is defined as positive, and current out of the device is defined as negative. All voltages are referenced to ground except $\mathrm{V}_{O D}$ and $\Delta \mathrm{V}_{\mathrm{OD}}$.
Note 3: AC parameters are guaranteed by design and characterization.
Note 4: $C_{L}$ includes probe and jig capacitance.
Note 5: Signal generator conditions: $V_{O L}=0, V_{O H}=V_{C C}, f=100 \mathrm{MHz}, 50 \%$ duty cycle, $R_{O}=50 \Omega$, $t_{R}=t_{F}=1 \mathrm{~ns}(10 \%$ to $90 \%)$.
Note 6: tSKD1 is the magnitude difference of differential propagation delays. tSKD1 = | tPHLD - tPLHD $\mid$.
Note 7: tSKD2 is the magnitude difference of tphLD or tPLHD of one channel to the tPHLD or tPLHD of another channel on the same device.
Note 8: $\operatorname{tSKD3}$ is the magnitude difference of any differential propagation delays between devices at the same $\mathrm{V}_{\mathrm{CC}}$ and within $5^{\circ} \mathrm{C}$ of each other.
Note 9: tSKD4 is the magnitude difference of any differential propagation delays between devices operating over the rated supply and temperature ranges.
Note 10: Signal generator conditions: $V_{O L}=0, V_{O H}=V_{C C}, f=100 \mathrm{MHz}, 50 \%$ duty cycle, $R_{O}=50 \Omega, t_{R}=t_{F}=1 n s(10 \%$ to $90 \%)$. MAX9129 output criteria: duty cycle $=45 \%$ to $55 \%$, VOD $\geq 250 \mathrm{mV}$, all channels switching.

## Quad Bus LVDS Driver with Flow-Through Pinout

(MAX9129EUE (TSSOP package), $\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=27 \Omega, \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.) (Note 5)


# Quad Bus LVDS Driver with Flow-Through Pinout 

## Typical Operating Characteristics (continued)

(MAX9129EUE (TSSOP package), $\mathrm{V}_{C C}=+3.3 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=27 \Omega, \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.) (Note 5)


## Quad Bus LVDS Driver with Flow-Through Pinout

| PIN |  | NAME | FUNCTION |
| :---: | :---: | :---: | :---: |
| QFN | TSSOP |  |  |
| 15 | 1 | EN | LVTTL/LVCMOS Enable Input. The driver is disabled when EN is low. EN is internally pulled down. When $\mathrm{EN}=$ high and $\overline{\mathrm{EN}}=$ low or open, the outputs are active. For other combinations of EN and $\overline{\mathrm{EN}}$, the outputs are disabled and are high impedance. |
| 1, 4, 5, 16 | 2, 3, 6, 7 | $\mathrm{IN}_{-}$ | LVTTL/LVCMOS Driver Inputs |
| 2 | 4 | VCC | Power-Supply Input. Bypass $\mathrm{V}_{\mathrm{CC}}$ to GND with $0.1 \mu \mathrm{~F}$ and $0.001 \mu \mathrm{~F}$ ceramic capacitors. |
| 3 | 5 | GND | Ground |
| 6 | 8 | $\overline{\mathrm{EN}}$ | LVTTL/LVCMOS Enable Input. The driver is disabled when $\overline{\mathrm{EN}}$ is high. $\overline{\mathrm{EN}}$ is internally pulled down. |
| 7, 10, 11, 14 | 9, 12, 13, 16 | OUT_- | Inverting BLVDS Driver Outputs |
| 8, 9, 12, 13 | 10, 11, 14, 15 | OUT_+ | Noninverting BLVDS Driver Outputs |



Figure 1. Driver VOD and VOS Test Circuit


Figure 2. Driver Propagation Delay and Transition Time Test Circuit


Figure 3. Driver Propagation Delay and Transition Time Waveforms

# Quad Bus LVDS Driver with Flow-Through Pinout 



Figure 4. Driver High-Impedance Delay Test Circuit

Table 1. Input/Output Function Table

| ENABLES |  | INPUTS | OUTPUTS |  |
| :---: | :---: | :---: | :---: | :---: |
| EN | $\overline{\mathrm{EN}}$ | $\mathrm{IN}_{-}$ | OUT_+ | OUT_- |
| $H$ | L or open | L | L | H |
|  | H | H | L |  |
| All other combinations of <br> EN and $\overline{\mathrm{EN}}$ | X | Z | Z |  |



Figure 5. Driver High-Impedance Delay Waveform

## Detailed Description

The MAX9129 is a 200 Mbps quad differential BLVDS driver designed for multipoint, heavily loaded backplane applications. This device accepts LVTTL/LVCMOS input levels and translates them to output levels of 250 mV to 450 mV into a $27 \Omega$ load. The flow-through pinout simplifies board layout and reduces the potential for crosstalk between single-ended inputs and differential outputs. Transition times are designed to reduce reflections, yet enable high data rates. The MAX9129 can be used in conjunction with standard quad LVDS receivers, such
as the MAX9121, to implement full-duplex multipoint buses more efficiently than with transceivers.

## Effect of Capacitive Loading

The characteristic impedance of a differential PC board trace is uniformly reduced when equal capacitive loads are attached at equal intervals (provided the transition time of the signal being driven on the trace is longer than the delay between loads). This kind of loading is typical of multipoint buses where cards are attached at 1 in or 0.8 in intervals along the length of a backplane.

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The reduction in characteristic impedance is approximated by the following formula:

$$
\begin{aligned}
& \text { ZDIFF-loaded }=\text { ZDIFF-unloaded } \times \text { SQRT [Co } /\left(C_{0}+N \times\right. \\
& C L / L)]
\end{aligned}
$$

where:
ZDIFF-unloaded $=$ unloaded differential characteristic impedance
$\mathrm{C}_{0}=$ unloaded trace capacitance ( $\mathrm{pF} /$ unit length)
$C_{L}=$ value of each capacitive load (pF)
$N$ = number of capacitive loads
$\mathrm{L}=$ trace length
For example, if $\mathrm{C}_{\mathrm{O}}=2.5 \mathrm{pF} / \mathrm{in}, \mathrm{C}_{\mathrm{L}}=10 \mathrm{pF}, \mathrm{N}=18, \mathrm{~L}=$ 18in, and ZDIFF-unloaded $=120 \Omega$, the loaded differential impedance is:

$$
\begin{aligned}
& \text { ZDIFF-loaded }=120 \Omega \times \text { SQRT }[2.5 \mathrm{pF} / \\
& (2.5 \mathrm{pF}+18 \times 10 \mathrm{pF} / 18 \mathrm{in})] \\
& \quad \text { ZDIFF-loaded }=54 \Omega
\end{aligned}
$$

In this example, capacitive loading reduces the characteristic impedance from $120 \Omega$ to $54 \Omega$. The load seen by a driver located on a card in the middle of the bus is $27 \Omega$ because the driver sees two $54 \Omega$ loads in parallel. A typical LVDS driver (rated for a $100 \Omega$ load) would not develop a large enough differential signal to be reliably detected by an LVDS receiver. Maxim's BLVDS driver is designed and specified to drive a $27 \Omega$ load to differential voltage levels of 250 mV to 450 mV (which are standard LVDS driver levels). A standard LVDS receiver is able to detect this level of differential signal.
Short extensions off the bus, called stubs, contribute to capacitive loading. Keep stubs less than 1in for a good balance between ease of component placement and good signal integrity.
The MAX9129 is a current source driver and drives larger differential signal levels into loads higher than $27 \Omega$ and smaller levels into loads less than $27 \Omega$ (see typical operating curves). To keep loading from reducing bus impedance below the rated $27 \Omega$ load, PC board traces can be designed for higher unloaded characteristic impedance.

Effect of Transition Time
For transition times (measured from 0\% to 100\%) shorter than the delay between capacitive loads, the loads are seen as low-impedance discontinuities from which the driven signal is reflected. Reflections add and subtract from the signal being driven and cause decreased noise margin and jitter. The MAX9129 is designed for a
minimum transition time of 1 ns (rated 0.6 ns from $20 \%$ to $80 \%$, or about 1 ns $0 \%$ to $100 \%$ ) to reduce reflections while being fast enough for high-speed backplane data transmission.

Power-On Reset The power-on reset voltage of the MAX9129 is typically 2.25 V . When the supply falls below this voltage, the device is disabled and the outputs are in high impedance.

## Applications Information

## Power-Supply Bypassing

Bypass VCc with high-frequency, surface-mount ceramic $0.1 \mu \mathrm{~F}$ and $0.001 \mu \mathrm{~F}$ capacitors in parallel as close to the device as possible, with the smaller valued capacitor closest to $\mathrm{V}_{\mathrm{C}}$.

Termination
In the example above, the loaded differential impedance of the bus is reduced to $54 \Omega$. Since it can be driven from any card position, the bus must be terminated at each end. A parallel termination of $54 \Omega$ at each end of the bus placed across the traces that make up the differential pair provides a proper termination. The total load seen by the driver is $27 \Omega$.
The MAX9129 drives higher differential signal levels into lighter loads. A multidrop bus with the driver at one end and receivers connected at regular intervals along the bus has a lowered impedance due to capacitive loading. Assuming the same impedance calculated in the multidrop example above ( $54 \Omega$ ), the multidrop bus can be terminated with a single, parallel-connected $54 \Omega$ resistor at the far end from the driver. Only a single resistor is required because the driver sees one $54 \Omega$ differential trace. The signal swing is larger with a $54 \Omega$ load.
In general, parallel terminate each end of the bus with a resistor matching the differential impedance of the bus (taking into account any reduced impedance due to loading).

Board Layout
A four-layer PC board that provides separate power, ground, input, and output signals is recommended. Keep the LVTTL/LVCMOS and BLVDS signals separated to prevent coupling as shown in the suggested layout for the QFN package (not drawn to scale) (Figure 6).

## Quad Bus LVDS Driver with Flow-Through Pinout



Figure 6. Suggested Layout for QFN Package

Chip Information
TRANSISTOR COUNT: 948
PROCESS: CMOS

# Quad Bus LVDS Driver with Flow-Through Pinout 



Functional Diagram


## Quad Bus LVDS Driver with Flow-Through Pinout



## Quad Bus LVDS Driver with Flow-Through Pinout



# Quad Bus LVDS Driver with <br> Flow－Through Pinout 

Package Information（continued）
NOTES：
1．DIE THICKNESS ALLOWABLE IS 0.305 mm MAXIMUM（． 012 INCHES MAXIMUM）
2．DIMENSIONING \＆TOLERANCES CONFORM MUST TO ASME Y14．5M．－ 1994.
3．$N$ IS THE NUMBER OF TERMINALS．
Nd IS THE NUMBER OF TERMINALS IN X－DIRECTION \＆
Ne IS THE NUMBER OF TERMINALS IN Y－DIRECTION．
4．DIMENSION b APPLIES TO PLATED TERMINAL AND IS MEASURED BETWEEN 0.20 AND 0.25 mm FROM TERMINAL TIP．
the pin \＃1 IDentifier must be existed on the top surface of the PACKAGE BY USING INDENTATION MARK OR OTHER FEATURE OF PACKAGE BODY．
6．EXACT SHAPE AND SIZE OF THIS FEATURE IS OPTIONAL
7．ALL DIMENSIONS ARE IN MILLIMETERS．
8．THE SHAPE SHOWN ON FOUR CORNERS ARE NOT ACTUAL I／O．
9．PACKAGE WARPAGE MAX 0.05 mm ．

|  | $\begin{array}{r} \text { COMMON } \\ \text { DIMENSIONS } \\ \hline \end{array}$ |  |  | $N_{O_{0}}$ |
| :---: | :---: | :---: | :---: | :---: |
|  | MIN． | NOM． | MAX． |  |
| A | － | 0.85 | 1.00 |  |
| A1 | 0.00 | 0.01 | 0.05 | 11 |
| A2 | － | 0.65 | 0.80 |  |
| A3 | 0．20 REF． |  |  |  |
| D | 4．00 BSC |  |  |  |
| D1 | 3．75 BSC |  |  |  |
| E | 4．00 BSC |  |  |  |
| E1 | 3．75 BSC |  |  |  |
| $\theta$ |  |  | $12^{\circ}$ |  |
| P | 0.24 | 0.42 | 0.60 |  |
| R | 0.13 | 0.17 | 0.23 |  |

10．APPLIED FOR EXPOSED PAD AND TERMINALS．
EXCLUDE EMBEDDING PART OF EXPOSED PAD FROM MEASURING．
11．APPLIED ONLY FOR TERMINALS．
12．MEETS JEDEC MO220．


| SYMBOLS | D2 |  |  | E2 |  |  | NOTE |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | NOM | MAX | MIN | NOM | MAX |  |
| EXPOSED PAD | A | 1.95 | 2.10 | 2.25 | 1.95 | 2.10 | 2.25 |  |
| VARIATIONS | B | 1.55 | 1.70 | 1.85 | 1.55 | 1.70 | 1.85 |  |

EXAMPLE：WE CAN CALL VARIATION＂BB＂FOR 16 TERMINAL QFN WITH $1.70 \times 1.70 \mathrm{~mm}$ NOMINAL EXPOSED PAD DIMENSION． THE FORMER ONE IN VARIATION IS FOR PITCH VARIATION AND THE LATTER ONE IS FOR EXPOSED PAD VARIATION．

PACKAGE QUTLINE， $12,16,20,24 \mathrm{~L}$ QFN， $4 \times 4 \times 0,90 \mathrm{MM}$ | APPROVAL | DOCUMENT CONTROL NO． | REV | $2 / 2$ |
| :--- | :---: | :---: | :---: |
|  | $21-0106$ | $B$ | 2 |

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