Hysteretic, Buck, High Brightness LED Driver with High-Side Current Sensing

Features

- ► Hysteretic control with high-side current sensing
- ▶ Wide input voltage range: 4.5 to 40V
- >90% Efficiency
- ► Typical ±5% LED current accuracy
- ▶ Up to 2.0MHz switching frequency
- Adjustable constant LED current
- Analog or PWM control signal for PWM dimming
- Over-temperature protection
- ► -40°C to +125°C operating temperature range
- ► AEC-Q100 compliant

Applications

Automotive LED lighting applications

General Description

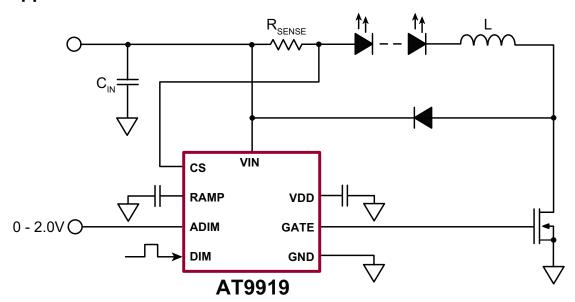
The AT9919 is a PWM controller IC designed to drive high brightness LEDs using a buck topology. It operates from an input voltage of 4.5 to 40VDC and employs hysteretic control with a high-side current sense resistor to set the constant output current.

The operating frequency range can be set by selecting the proper inductor. Operation at high switching frequency is possible since the hysteretic control maintains accuracy even at high frequencies. This permits the use of small inductors and capacitors minimizing space and cost in the overall system.

LED brightness control is achieved with PWM dimming from an analog or PWM input signal. Unique PWM circuitry allows true constant color with a high dimming range. The dimming frequency is programmed using a single external capacitor.

The AT9919 comes in a small, 8-Lead DFN package and is qualified for automotive LED lighting applications.

Typical Application Circuit



Ordering Information

Part Number	Package	Packing
AT9919K7-G	8-Lead DFN	3000/Reel

-G indicates package is RoHS compliant ('Green')

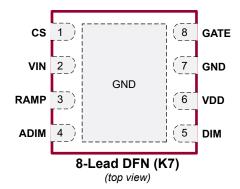


Absolute Maximum Ratings

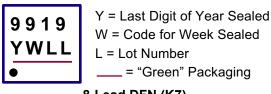
Parameter	Value
VIN, CS to GND	-0.3 to +45V
VDD, GATE, RAMP, DIM, ADIM to GND	-0.3 to +6.0V
CS to VIN	-1.0 to +0.3V
Continuous power dissipation, $(T_A = +25^{\circ}C)$	1.6W
Operating temperature range	-40°C to +125°C
Junction temperature	+150°C
Storage temperature range	-65°C to +150°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Pin Description



Product Marking



8-Lead DFN (K7)

Typical Thermal Resistance

Package	$oldsymbol{ heta}_{ja}$					
8-Lead DFN	37°C/W					

Mounted on FR-4 board, 25mm x 25mm x 1.57mm

Electrical Characteristics

 $(V_{NN} = 12V, V_{DIM} = V_{DD}, V_{RAMP} = GND, C_{VDD} = 1.0\mu F, R_{CS} = 0.5\Omega, T_{A} = T_{J} = -40^{\circ}\text{C}$ to +125°C* unless otherwise noted)

Sym	Description	Min	Тур	Max Un		Conditions
V _{IN}	Input DC supply voltage range	4.5	_	40	V	DC input voltage
V _{DD}	Internally regulated voltage	4.5	-	5.5	V	$V_{IN} = 6.0 \text{ to } 40 \text{V}$
I _{IN}	Supply current	-	-	1.5	mA	GATE open
I _{IN, SDN}	Shutdown supply current	-	-	900	μA	DIM < 0.7V
	Current limit	-	30	-	mA	$V_{IN} = 4.5 V, V_{DD} = 0 V$
I _{IN, LIM}	Current mint	-	8.0	-	IIIA	$V_{IN} = 4.5 V, V_{DD} = 4.0 V$
f _{osc}	Oscillator frequency	-	_	2.0	MHz	
UVLO	V _{DD} Undervoltage lockout threshold	-	-	4.5	V	V _{DD} rising
ΔUVLO	ΔUVLO V _{DD} Undervoltage lockout hysteresis		500	-	mV	V _{DD} falling

 $^{^*}$ Guaranteed by design and characterization, 100% tested at $T_{\scriptscriptstyle A}$ = 25 $^{\circ}$ C. Typical characteristics are given at $T_{\scriptscriptstyle A}$ = 25 $^{\circ}$ C.

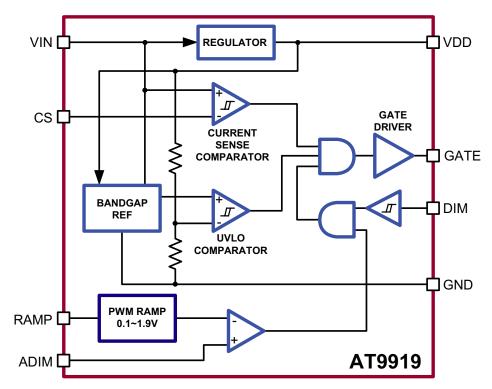
Electrical Characteristics $(V_{IN}=12V,\ V_{DIM}=V_{DD},\ V_{RAMP}=GND,\ C_{VDD}=1.0\mu F,\ R_{CS}=0.5\Omega,\ T_A=T_J=-40^{\circ} C\ to\ +125^{\circ} C^*\ unless\ otherwise\ noted)$

Sym	Description	Min	Тур	Max	Units	Conditions
Sense C	omparator	1	ı	1		
$V_{\text{CS(HI)}}$	Sense voltage threshold high	198	230	257	mV	(V _{IN} - V _{CS}) rising
V _{CS(LO)}	Sense voltage threshold low	147	170	195	mV	(V _{IN} - V _{CS}) falling
V _{CS(AVG)}	Average reference voltage	186	200	214	mV	$V_{CS(AVG)} = 0.5V_{CS(HI)} + 0.5V_{CS(LO)}$
t _{DPDH}	Propagation delay to output high	-	70	-	ns	Falling edge of $(V_{IN} - V_{CS}) = V_{RS(LO)} - 70 \text{mV}$
t _{DPDL}	Propagation delay to output low	-	70	-	ns	Rising edge of $(V_{IN} - V_{CS}) = V_{RS(HI)} + 70 \text{mV}$
I _{cs}	Current-sense input current	-	-	1.0	μA	$(V_{IN} - V_{CS}) = 200 \text{mV}$
$V_{\text{CS(HYS)}}$	Current-sense threshold hysteresis	-	56	80	mV	
DIM Inpu	ut				'	
V _{IH}	Pin DIM input high voltage	2.2	-	-	V	
V _{IL}	Pin DIM input low voltage	-	-	0.7	V	
t _{on}	Turn-on time	-	100	-	ns	DIM rising edge to V _{GATE} = 0.5 x V _{DD} , C _{GATE} = 2.0nF
t _{OFF} Turn-off time		-	100	-	ns	DIM falling edge to $V_{GATE} = 0.5 \times V_{DD}, C_{GATE} = 2.0nF$
Gate Dri	ver					
	GATE current, source [†]	0.3	0.5	-	Α	V _{GATE} = GND
GATE	GATE current, sink [†]	0.7	1.0	-	Α	V _{GATE} = V _{DD}
T_{RISE}	GATE output rise time	-	40	55	ns	C _{GATE} = 2.0nF
T_{FALL}	GATE output fall time	-	17	25	ns	C _{GATE} = 2.0nF
$V_{\text{GATE(HI)}}$	GATE high output voltage	V _{DD} -0.5	-	-	V	I _{GATE} = 10mA
$V_{\text{GATE(LO)}}$	GATE low output voltage	-	-	0.5	V	I _{GATE} = -10mA
	mperature Protection					
T _{ot}	Over temperature trip limit [†]	128	140	-	°C	
ΔT_{HYST}	Temperature hysteresis [†]	-	60	-	°C	
	Control of PWM Dimming					
f	Dimming frequency	130	-	300 Hz		C _{RAMP} = 47nF
f _{RAMP}	Dimining inequality	550	-	1250	112	C _{RAMP} = 10nF
V_{LOW}	V _{LOW} RAMP threshold, Low		0.1	-	V	
V_{HiGH}	RAMP threshold, High	1.8	-	2.1	V	
V_{os}	ADIM offset voltage	-35	-	+35	mV	

^{*} Guaranteed by design and characterization, 100% tested at T_A = 25°C. Typical characteristics are given at T_A = 25°C.

[†] Guaranteed by design and characterization.

Block Diagram



Application Information

General Description

The AT9919 is a step-down, constant current, high-brightness LED (HB LED) driver. The device operates from a 4.5 to 40V input voltage range and provides the gate drive output to an external N-channel MOSFET. A high-side current sense resistor sets the output current and a dedicated PWM dimming input (DIM) allows for a wide range of diming duty ratios. The PWM dimming could also be achieved by applying a DC voltage between 0 and 2.0V to the analog dimming input (ADIM). In this case, the dimming frequency can be programmed using a single capacitor at the RAMP pin. The high-side current setting and sensing scheme minimizes the number of external components while delivering LED current with a ±8% accuracy, using a 1% sense resistor.

Undervoltage Lockout (UVLO)

The AT9919 includes a 3.7V under-voltage lockout (UVLO) with 500mV hysteresis. When $V_{\rm IN}$ falls below 3.7V, GATE goes low, turning off the external n-channel MOSFET. GATE goes high once $V_{\rm IN}$ is 4.5V or higher.

5.0V Regulator

VDD is the output of a 5.0V regulator capable of sourcing 8.0mA. Bypass VDD to GND with a 1.0µF capacitor.

DIM Input

The AT9919 allows dimming with a PWM signal at the DIM input. A logic level below 0.7V at DIM forces the $GATE_{OUTPUT}$ low, turning off the LED current. To turn the LED current on, the logic level at DIM must be at least 2.2V.

ADIM and RAMP Inputs

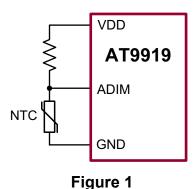
The PWM dimming scheme can be also implemented by applying an analog control signal to ADIM pin. If an analog control signal of 0~2.0V is applied to ADIM, the device compares this analog input to a voltage ramp to pulse-width-modulate the LED current. Connecting an external capacitor to RAMP programs the PWM dimming ramp frequency.

$$f_{PWM} = \frac{1}{C_{RAMP} \cdot 120k\Omega}$$

DIM and ADIM inputs can be used simultaneously. In such case, $f_{\text{PWM}(\text{MAX})}$ must be selected lower than the frequency of the dimming signal at DIM. The smaller dimming duty cycle of ADIM and DIM will determine the GATE signal.

When the analog control of PWM dimming feature is not used, RAMP must be wired to GND, and ADIM should be connected to VDD.

One possible application of the ADIM feature of the AT9919 may include protection of the LED load from over-temperature by connecting an NTC thermistor at ADIM, as shown in Figure 1.



Setting LED Current with External Resistor R_{SENSE}

The output current in the LED is determined by the external current sense resistor (R_{SENSE}) connected between VIN and CS. Disregarding the effect of the propagation delays, the sense resistor can be calculated as:

$$R_{SENSE} \approx \frac{1}{2} \cdot \frac{(V_{RS(HI)} + V_{RS(LO)})}{I_{LED}} = \frac{200mV}{I_{LED}}$$

Selecting Buck Inductor L

The AT9919 regulates the LED output current using an input

comparator with hysteresis (Figure 2). As the current through the inductor ramps up and the voltage across the sense resistor reaches the upper threshold, the voltage at GATE goes low, turning off the external MOSFET. The MOSFET turns on again when the inductor current ramps down through the freewheeling diode until the voltage across the sense resistor equals the lower threshold. Use the following equation to determine the inductor value for a desired value of operating frequency $f_{\rm s}$:

$$L = \frac{(V_{IN} - V_{OUT})V_{OUT}}{f_{S}V_{IN}\Delta I_{O}} - \frac{(V_{IN} - V_{OUT})t_{DPDL}}{\Delta I_{O}} - \frac{V_{OUT}t_{DPDH}}{\Delta I_{O}}$$

where:

$$\Delta I_{\rm O} = \frac{V_{\rm RS(HI)} - V_{\rm RS(LO)}}{R_{\rm SENSE}}$$

and \mathbf{t}_{DPDL} , \mathbf{t}_{DPDH} are the propagation delays. Note, that the current ripple $\Delta \mathbf{I}$ in the inductor L is greater than $\Delta \mathbf{I}_{\text{O}}$. This ripple can be calculated from the following equation:

$$\Delta I = \Delta I_{O} + \frac{(V_{IN} - V_{OUT})t_{DPDL}}{L} + \frac{V_{OUT}t_{DPDH}}{L}$$

For the purpose of the proper inductor selection, note that the maximum switching frequency occurs at the highest V_{IN} and $V_{OUT} = V_{IN}/2$.

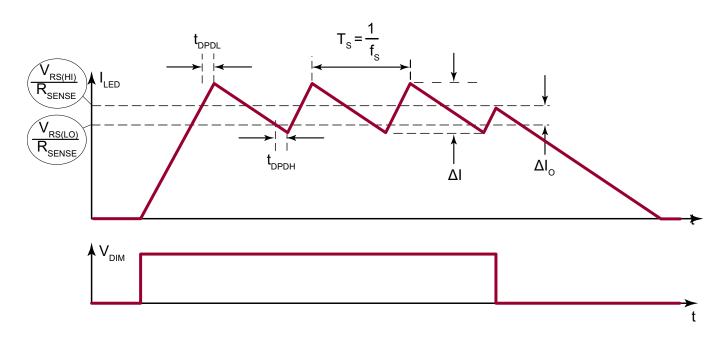


Figure 2

MOSFET Selection

MOSFET selection is based on the maximum input operating voltage V_{IN} , output current I_{LED} , and operating switching frequency. Choose a MOSFET that has a higher breakdown voltage than the maximum operation voltage, low $R_{\text{DS(ON)}}$, and low total charge for better efficiency. MOSFET threshold voltage must be adequate if operated at the low end of the input-voltage operating range.

Freewheeling Diode Selection

The forward voltage of the freewheeling diode should be as low as possible for better efficiency. A Schottky diode is a good choice as long as the breakdown voltage is high enough to withstand the maximum operating voltage. The forward current rating of the diode must be at least equal to the maximum LED current.

LED Current Ripple

The LED current ripple is equal to the inductor current ripple. In cases when a lower LED current ripple is needed, a capacitor can be placed across the LED terminals.

PCB Layout Guidelines

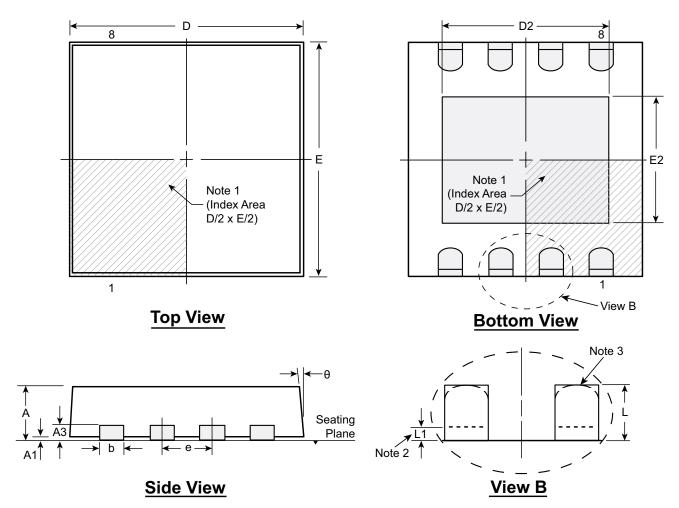
Careful PCB layout is critical to achieve low switching losses and stable operation. Use a multilayer board whenever possible for better noise immunity. Minimize ground noise by connecting high-current ground returns, the input bypass capacitor ground lead, and the output filter ground lead to a single point (star ground configuration). The fast di/dt loop is formed by the input capacitor $C_{_{\rm IN}}$, the free-wheeling diode and the MOSFET. To minimize noise interaction, this loop area should be as small as possible. Place $R_{_{\rm SENSE}}$ as close as possible to the input filter and VIN. For better noise immunity, a Kelvin connection is strongly recommended between CS and $R_{_{\rm SENSE}}$. Connect the exposed tab of the IC to a largearea ground plane for improved power dissipation.

Pin Description

Pin#	Pin	Description		
1	CS	Current sense input. Senses LED string current.		
2	2 VIN Input voltage 4.5 to 40VDC.			
3	RAMP	Analog PWM dimming ramp output.		
4	ADIM	Analog 0~2.0V signal input for analog control of PWM dimming.		
5 DIM PWM signal input. 6 VDD Internally regulated supply voltage. Conf		PWM signal input.		
		Internally regulated supply voltage. Connect a capacitor from VDD to ground.		
7	GND	Device ground.		
8	GATE	Drives gate of external MOSFET.		
TAB	GND	Must be wired to pin 7 on PCB.		

8-Lead DFN Package Outline (K7)

3.00x3.00mm body, 0.80mm height (max), 0.65mm pitch



Notes:

- A Pin 1 identifier must be located in the index area indicated. The Pin 1 identifier can be: a molded mark/identifier; an embedded metal marker; or a printed indicator.
- 2. Depending on the method of manufacturing, a maximum of 0.15mm pullback (L1) may be present.
- The inner tip of the lead may be either rounded or square.

Symbo	ol	Α	A1	А3	b	D	D2	E	E2	е	L	L1	θ
	MIN	0.70	0.00	0.20 REF	0.25	2.85*	1.60	2.85*	1.35	0.65 BSC	0.30	0.00*	0°
Dimension (mm)	NOM	0.75	0.02		0.30	3.00	-	3.00	-		0.40	-	-
	MAX	0.80	0.05		0.35	3.15*	2.50	3.15*	1.75		0.50	0.15	14º

JEDEC Registration MO-229, Variation WEEC-2, Issue C, Aug. 2003.

Drawings not to scale.

Supertex Doc. #: DSPD-8DFNK73X3P065, Version C081109.

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to http://www.supertex.com/packaging.html.)

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^{*} This dimension is not specified in the JEDEC drawing.

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